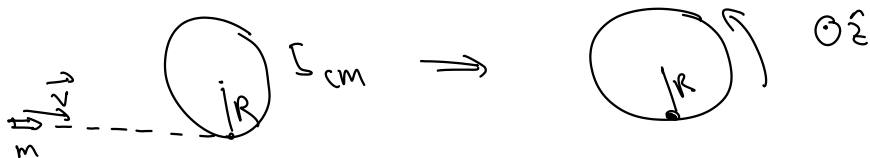


Example

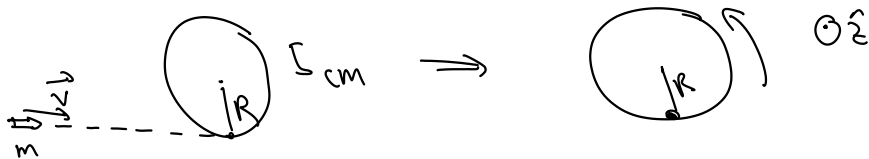


Energy Conservation

$$K_i = \frac{1}{2} m v^2$$

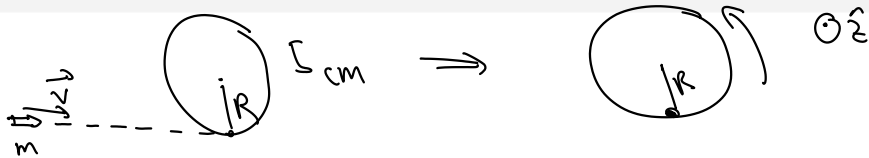
$$K_f = \frac{1}{2} I_{cm} \omega^2 + \frac{1}{2} m (\omega R)^2$$

$$\text{if } K_i = K_f \Rightarrow \frac{1}{2} m v^2 = \frac{1}{2} (I_{cm} + m R^2) \omega^2$$



Conservation of momentum. X

$$\frac{d\vec{p}_{cm}}{dt} = \vec{F}_{ext}$$



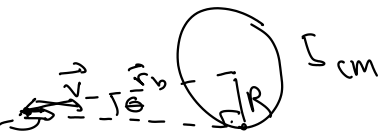
Conservation of angular mom:

$$\frac{d\vec{L}}{dt} = \vec{\tau}_{\text{ext}} \quad \vec{\tau}_{\text{ext}} = \sum \vec{r} \times \vec{F}_{\text{ext}}$$

$$\vec{L} = \sum_i \vec{r}_i \times \vec{p}_i \quad \text{origin on the axis}$$

$$\vec{\tau} = 0 \Rightarrow \vec{L} \text{ is conserved}$$

$$I = \sum m_i R_i^2$$



$$\begin{aligned} \vec{L}_i &= \sum \vec{r}_i \times \vec{p}_i \\ &= \vec{r}_b \times (m\vec{v}) \\ &= r_b m v \sin(\alpha - \theta) \hat{z} \\ \vec{L}_i &= m v r_b \sin\theta \hat{z} \\ &= m v R \hat{z} \end{aligned}$$



$$\begin{aligned} \vec{L}_p &= \sum \vec{r}_i \times \vec{p}_i \\ &= I_{cm} \vec{\omega} + m R^2 \vec{\omega} \\ &= (I_{cm} + m R^2) \omega \hat{z} \\ &= m v R \hat{z} \end{aligned}$$

$$\Rightarrow \omega = \frac{m v R}{I_{cm} + m R^2}$$

$$K_i = \frac{1}{2} m v^2$$

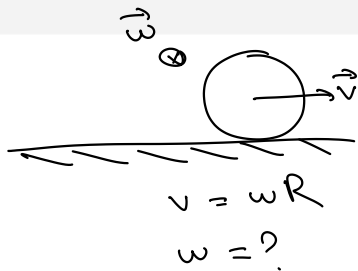
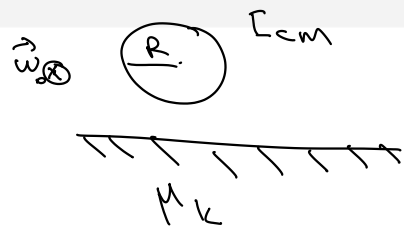
$$\Rightarrow \omega = \frac{m v R}{I_{cm} + m R^2}$$

$$K_f = \frac{1}{2} I_{cm} \omega^2 + \frac{1}{2} m (\omega R)^2$$

$$= \frac{1}{2} \frac{(\cancel{I_{cm} + m R^2}) (m v R)^2}{(I_{cm} + m R^2)^2} = \frac{1}{2} m v^2 \left[\frac{m R^2}{I_{cm} + m R^2} \right]$$

$$K_f - K_i = \frac{1}{2} m v^2 \left[\frac{m R^2}{I_{cm} + m R^2} - 1 \right]$$

$$= \frac{1}{2} m v^2 \left(\frac{-I_{cm}}{I_{cm} + m R^2} \right)$$



Energy \times
 Linear momentum \times
 Angular momentum ?



$$\vec{\tau}_{\text{net}} = ?$$

$$\vec{\tau} = \vec{r} \times \vec{F}$$

$$\neq 0$$

$$\vec{\tau}_0 = 0$$

$$|\vec{\tau}| = r F \sin \theta$$

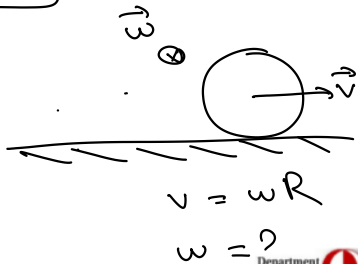
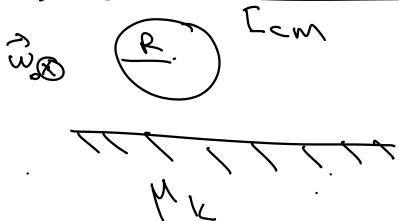
$$\left. \begin{aligned} \vec{\tau}_0 &= N d \\ \vec{\tau}_0 &= W d \end{aligned} \right\} N = W$$

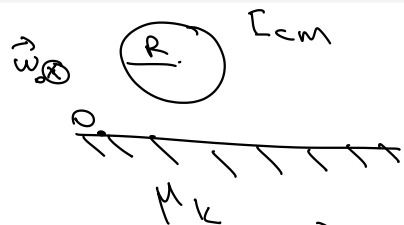
$$\vec{\tau}_0 = 0 \Rightarrow \frac{d\vec{L}}{dt} = 0 \Rightarrow \vec{L} \text{ is conserved}$$



$$\frac{d\vec{p}}{dt} = \vec{F}_{ext} = \vec{F}_F \neq 0$$

$$\vec{L} = \vec{r}_{cm} \times \vec{p}_{cm} + \vec{L}_{cm}$$



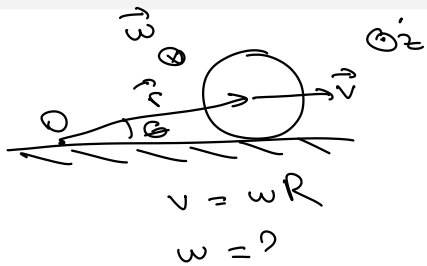


$$\vec{L} = \vec{r}_{cm} \times \vec{p}_{cm} + \vec{L}_{cm}$$

$$\vec{L}_i = \vec{L}_{cm} \vec{\omega}_0$$

$$\vec{\omega}_0 = \omega_0 (-\hat{z})$$

$$\vec{L}_i = -I_{cm} \omega_0 \hat{z}$$



$$v = \omega R$$

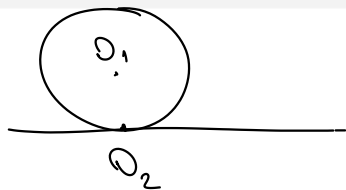
$$\omega = ?$$

$$\vec{L}_f = Rm v (-\hat{z}) + \vec{L}_{cm} \vec{\omega}$$

$$\vec{\omega} = \omega (-\hat{z})$$

$$\vec{L}_f = (-m v R^2 - I_{cm} \omega) \hat{z}$$

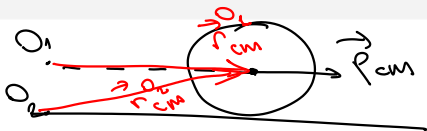
$$\omega = \frac{I_{cm} \omega_0}{I_{cm} + m R^2} < \omega_0$$



$$\vec{L}_{O_1} = I \vec{\omega}_0$$

$$\vec{L}_{O_2} = I \vec{\omega}_0$$

$$\vec{L} = \vec{r}_{cm} \times \vec{p}_{cm} + \vec{L}_{cm}$$



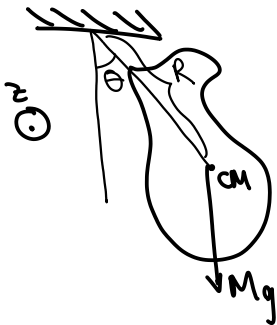
$$\vec{L}_{O_1} = I \vec{\omega}$$

$$\vec{L}_{O_2} = \vec{r}_{cm} \times \vec{p}_{cm} + I \vec{\omega}$$

$$\vec{r}_{cm}^{O_1} \times \vec{p}_{cm} = 0$$

$$\vec{r}_{cm}^{O_2} \times \vec{p}_{cm} \neq 0$$

Oscillations



Let I_{cm} be the moment of inertia around CM.

$$I = I_{cm} + MR^2$$

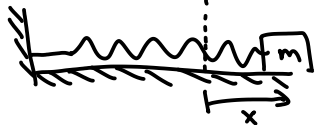
$$\vec{\tau} = -MgR \sin \theta \hat{z}$$

$$\vec{\alpha} = \frac{d^2 \theta}{dt^2} \hat{z}$$

$$-MgR \sin \theta = I \frac{d^2 \theta}{dt^2}$$

For $\theta \ll 1$, $\sin \theta \approx \theta$

$$\frac{d^2 \theta}{dt^2} + \left(\frac{MgR}{I} \right) \theta = 0$$



$$F = -kx$$

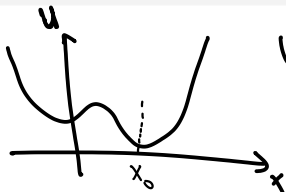
$$m \frac{d^2 x}{dt^2} = -kx$$

$$\frac{d^2 x}{dt^2} + \left(\frac{k}{m}\right)x = 0$$

Compare with:

$$\frac{d^2 \theta}{dt^2} + \left(\frac{MgR}{I}\right)\theta = 0$$

Motion Close to a Minimum of Potential



$$U(x) = U(x_0) + \left. \frac{dU}{dx} \right|_{x=x_0} (x-x_0) + \left. \frac{d^2U}{dx^2} \right|_{x=x_0} \frac{(x-x_0)^2}{2} + \dots$$

If x_0 is a minimum

$$\left. \frac{dU}{dx} \right|_{x=x_0} = 0 \quad \& \quad \left. \frac{d^2U}{dx^2} \right|_{x=x_0} > 0$$

Then $U(x) \approx U(x_0) + \frac{1}{2} \left. \frac{d^2U}{dx^2} \right|_{x=x_0} (x-x_0)^2$

$$F(x) \approx - \frac{dU}{dx} = -k(x-x_0)$$

where $k = \left. \frac{d^2U}{dx^2} \right|_{x=x_0}$. This is nothing but

Hook's Law

In physics, close to minimum energy everything behaves like a spring!