

EE-463 STATIC POWER CONVERSION-I

Controlled Rectifiers

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Thyristor Rectifiers

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- . HVDC Transmission Systems

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- . DC Motor Drives

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- HVDC Transmission Systems
- DC Motor Drives
- Traction Applications

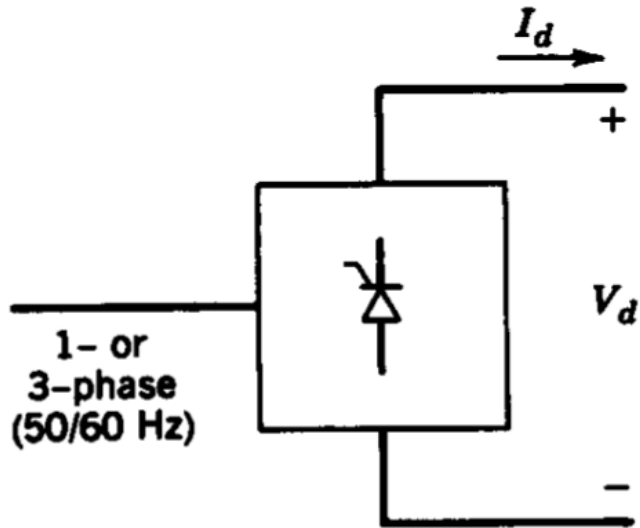
Thyristor Rectifiers

- HVDC Transmission Systems
- DC Motor Drives
- Traction Applications
- Industrial Loads (Welding, Heating etc)

Thyristor Rectifiers

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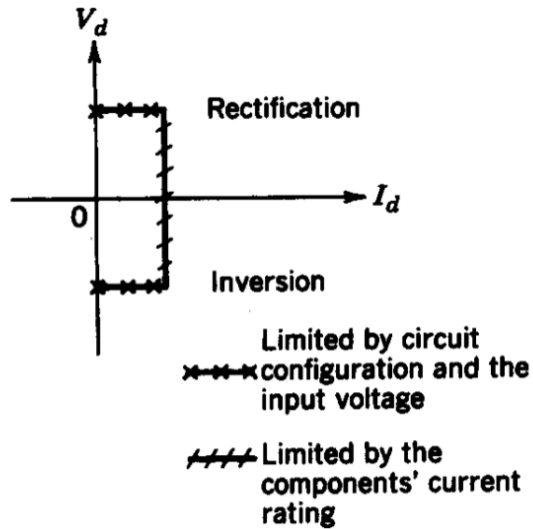
General Schematic



Thyristor Rectifiers

Thyristor Rectifiers

Operating Quadrants

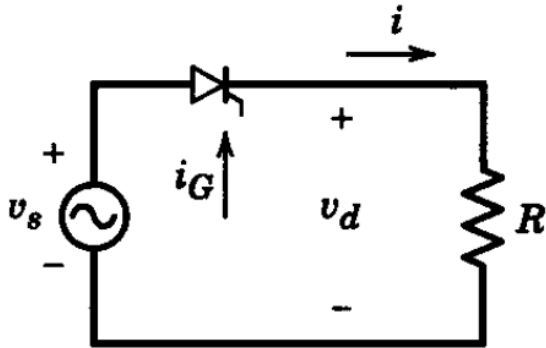


Capable of supplying negative V_d (Q4, Inversion)

Simple Circuits

Simple Circuits

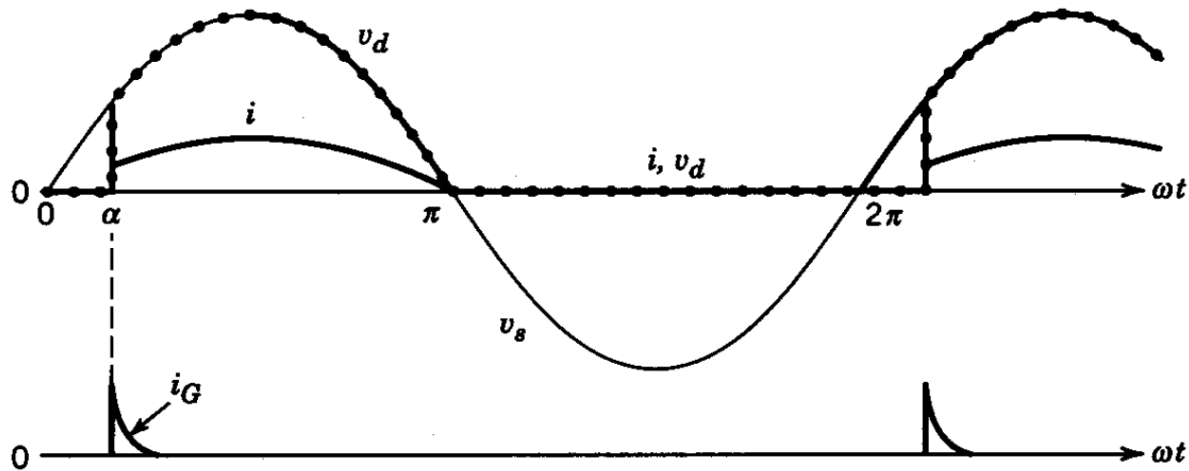
Thyristor with R load



Can you plot the voltage output?

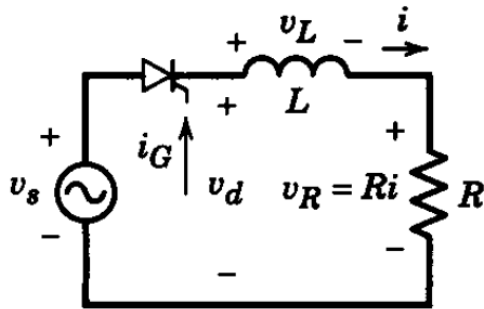
Simple Circuits

Thyristor with R load



Simple Circuits

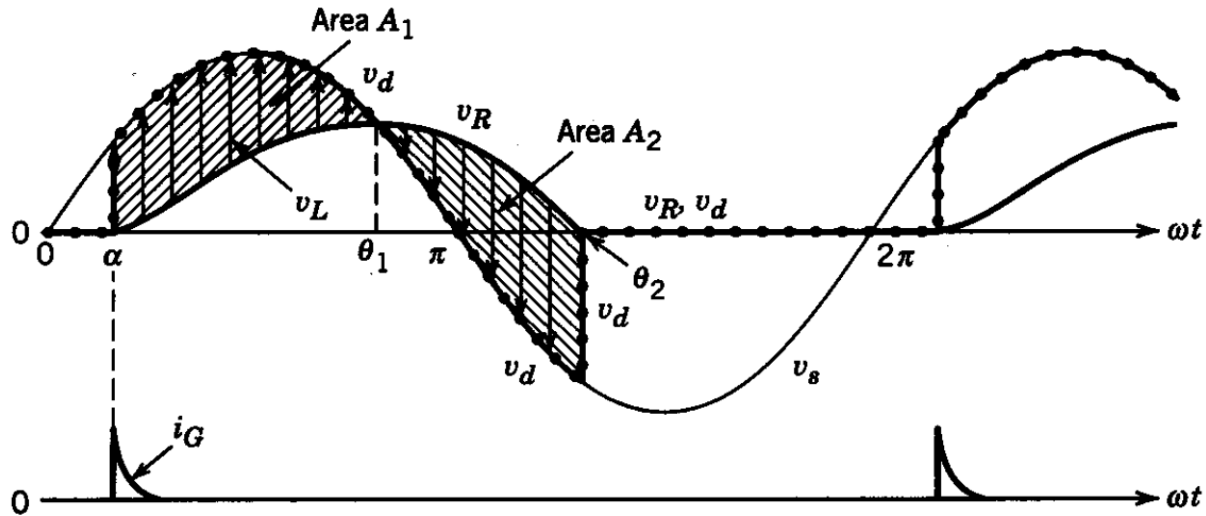
Thyristor with RL load



Can you plot the voltage output?

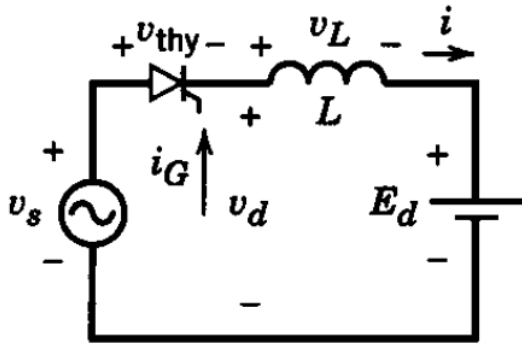
Simple Circuits

Thyristor with RL load



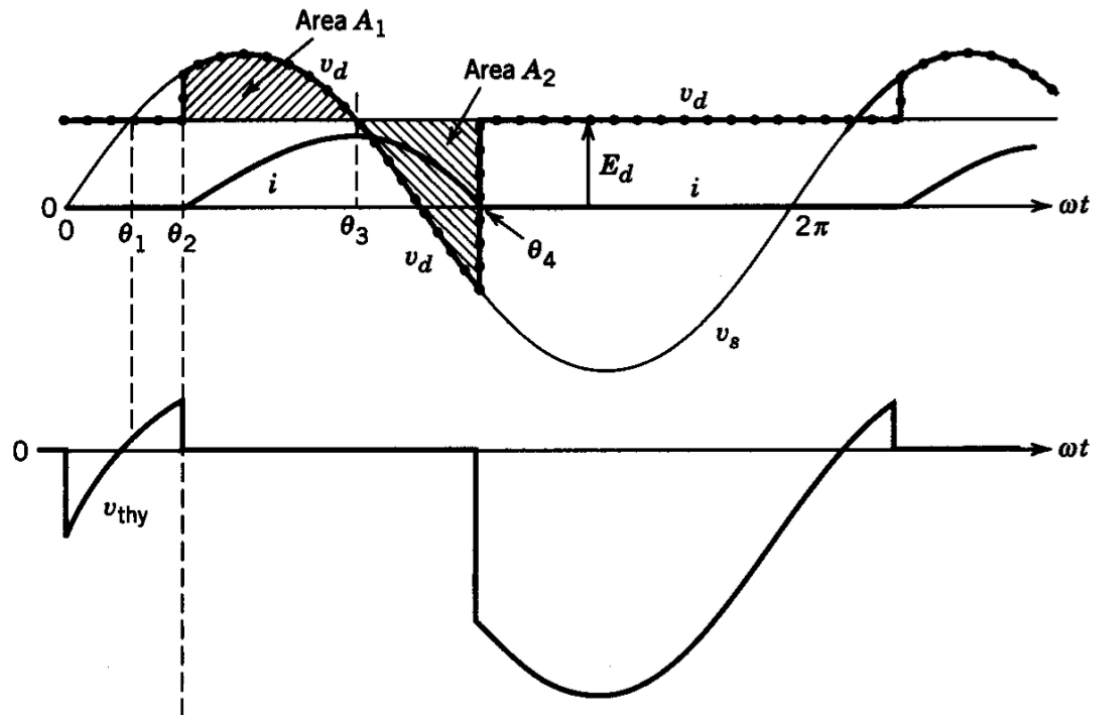
Simple Circuits

Load with DC Source



Can you plot the voltage output?

Load with DC Source

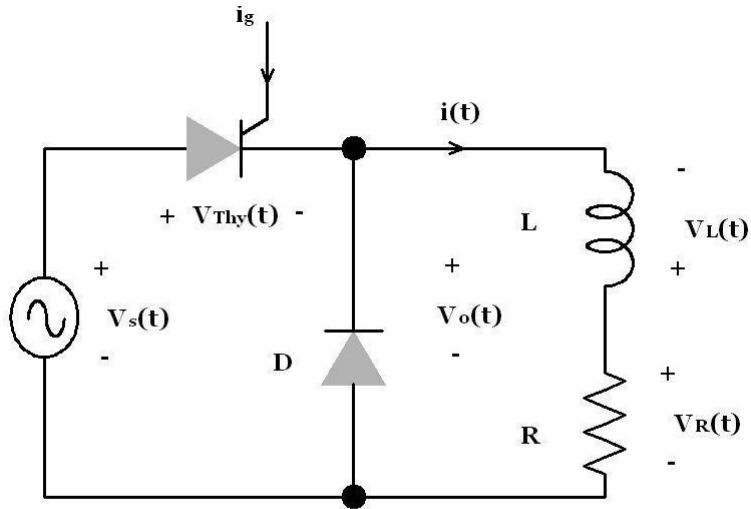


Thyristor with RL load

but let's add a freewheeling diode

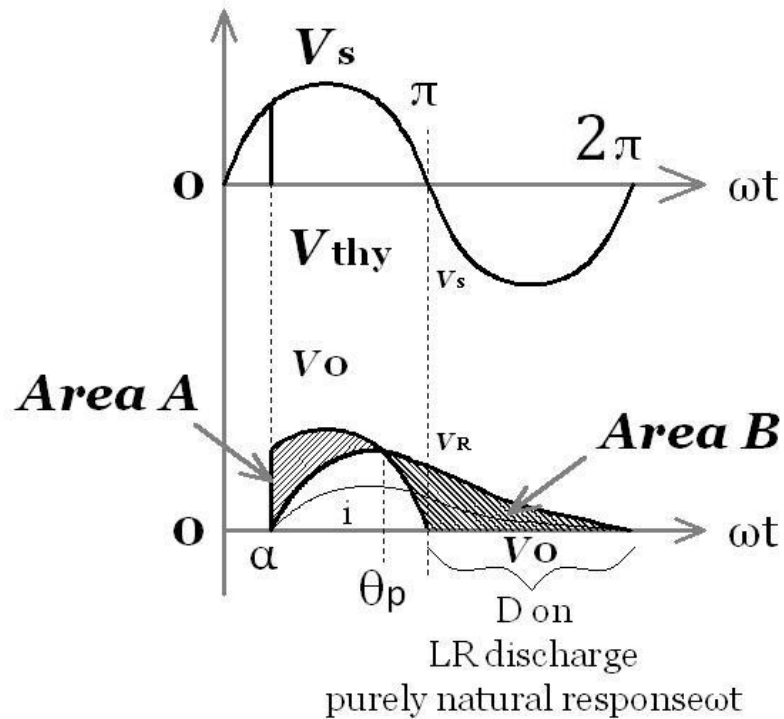
Thyristor with RL load

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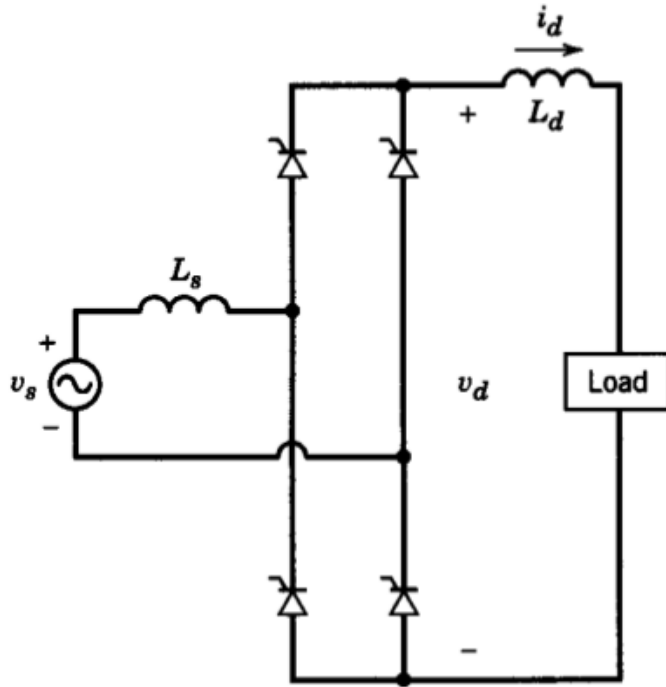
Thyristor with freewheeling diode

Thyristor with freewheeling diode



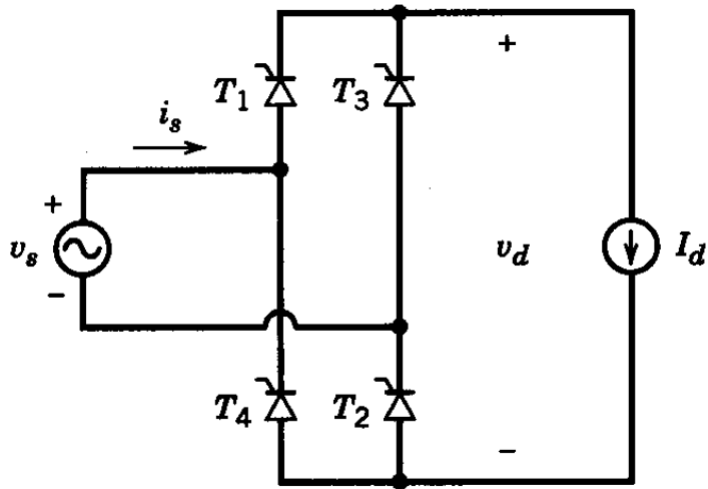
Single Phase Thyristor Rectifier

Single Phase Thyristor Rectifier



Single Phase Thyristor Rectifier

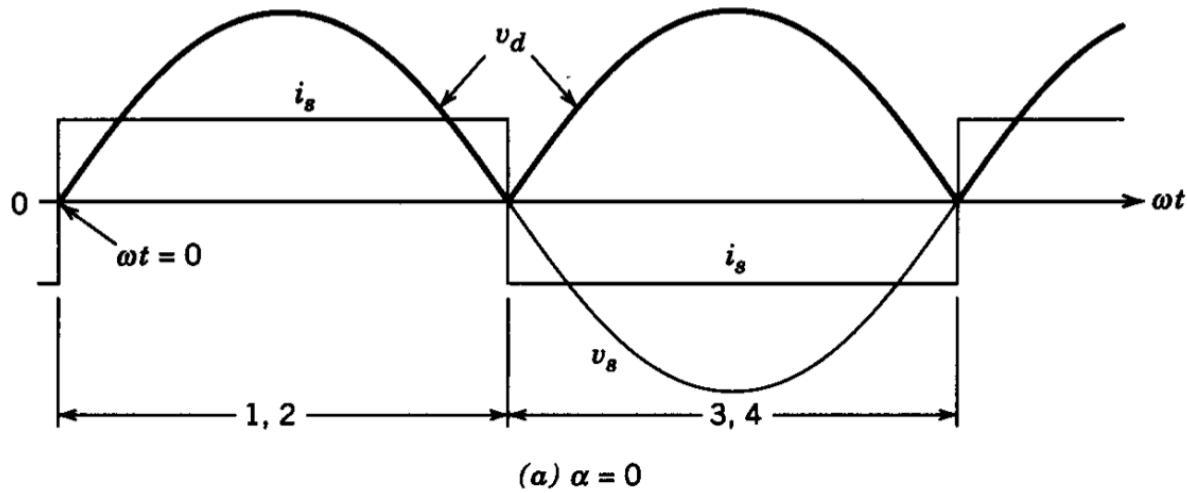
Ideal Case



Can you plot the output voltages?

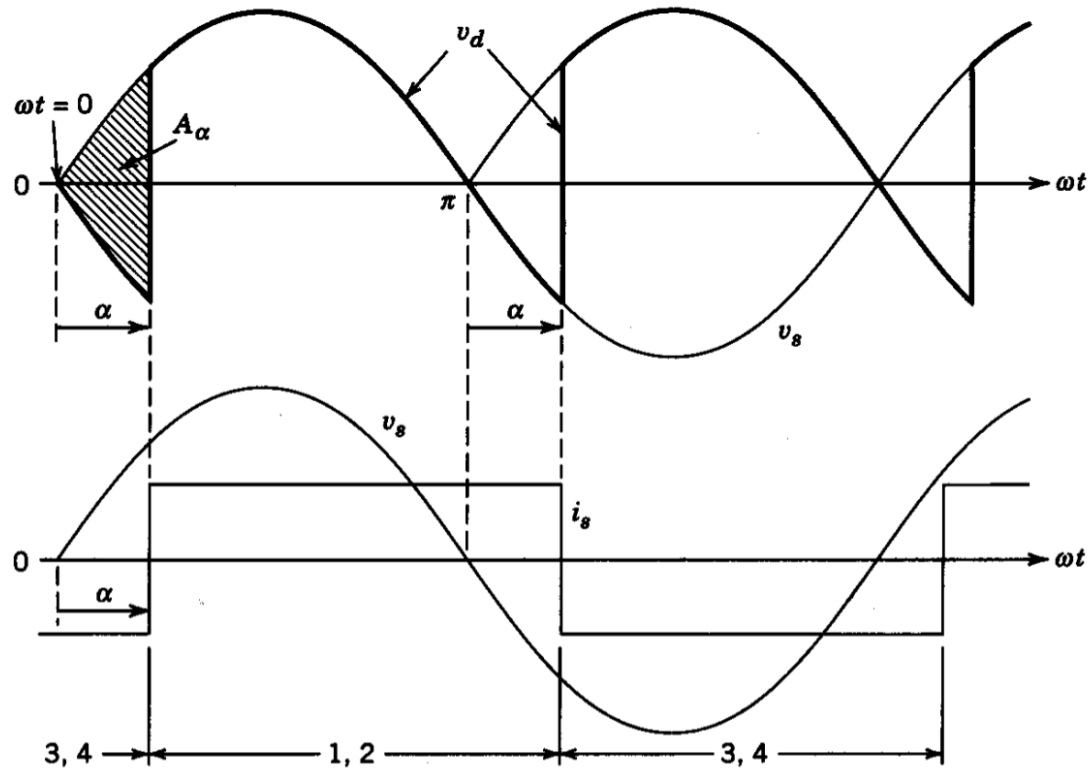
It is identical to diode rectifier with $\alpha = 0$

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What about with a large firing angle?

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How can you calculate the average voltage?

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• $\alpha = 0 \rightarrow$ Diode rectifier

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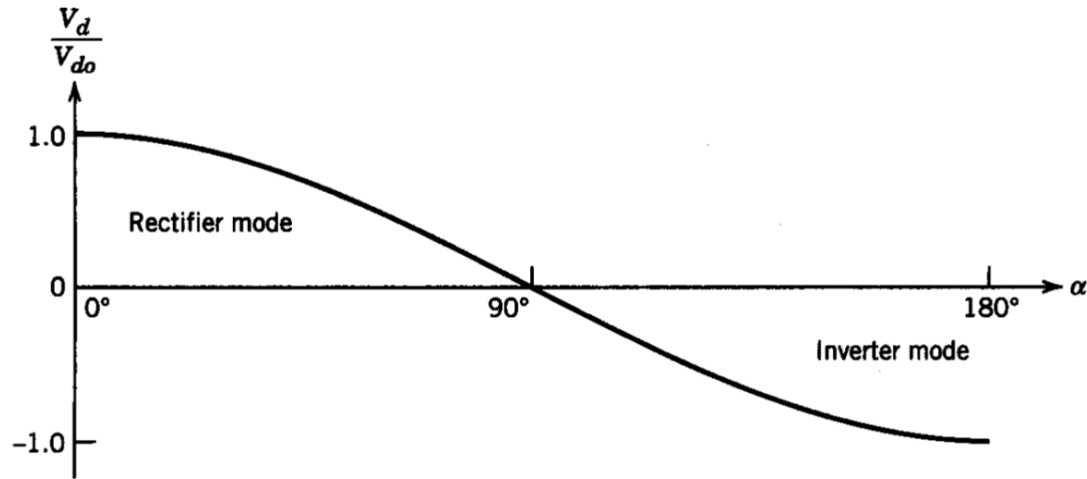
- $\alpha = 0 \rightarrow$ Diode rectifier
- $\alpha < \pi/2 \rightarrow V_d > 0$

How can you calculate the average voltage?

$$V d_{\alpha} = \frac{2\sqrt{2}V_s}{\pi} \cos(\alpha)$$

- $\alpha = 0 \rightarrow$ Diode rectifier
- $\alpha < \pi/2 \rightarrow V d > 0$
- $\alpha > \pi/2 \rightarrow V d < 0$

Operating Modes



Power Flow

Power Flow

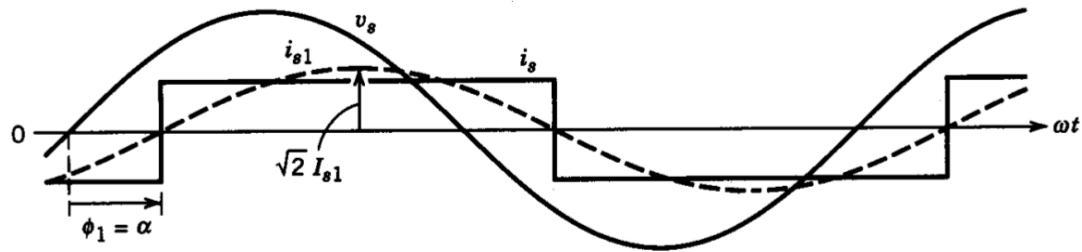
$$P = \frac{1}{T} \int p(t) dt$$

Power Flow

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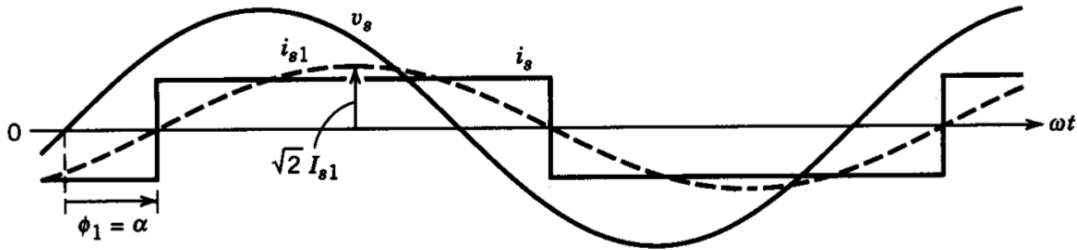
$$P = I_d \frac{1}{T} \int v_d(t) dt = 0.9 V_s I_d \cos(\alpha)$$

Line Current



Shifted by α , but still a square wave

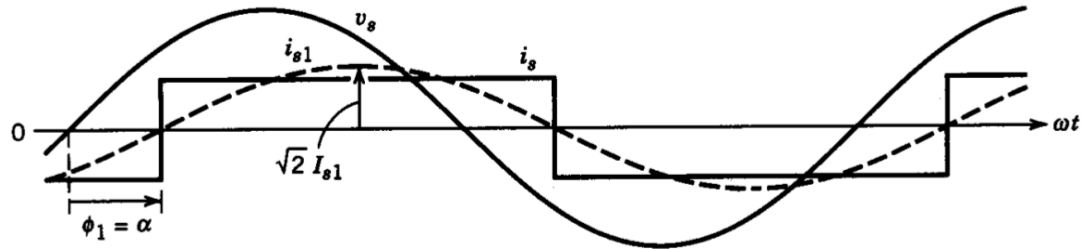
Line Current



Shifted by α , but still a square wave

Harmonics, THD, I_1 ?

Line Current



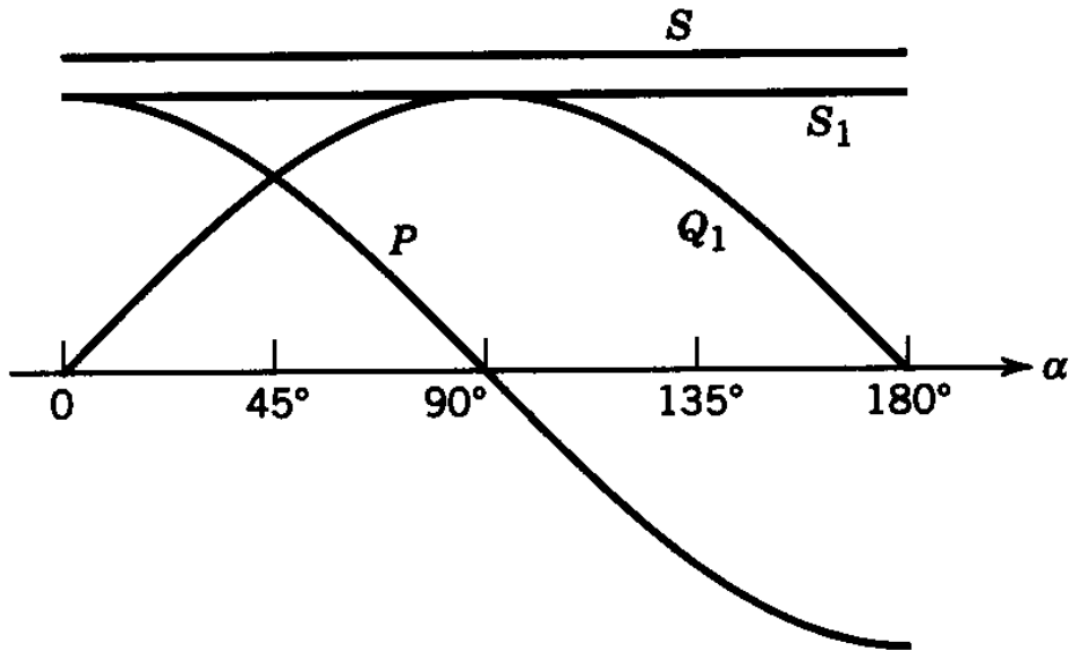
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Harmonics, THD, I_1 ?

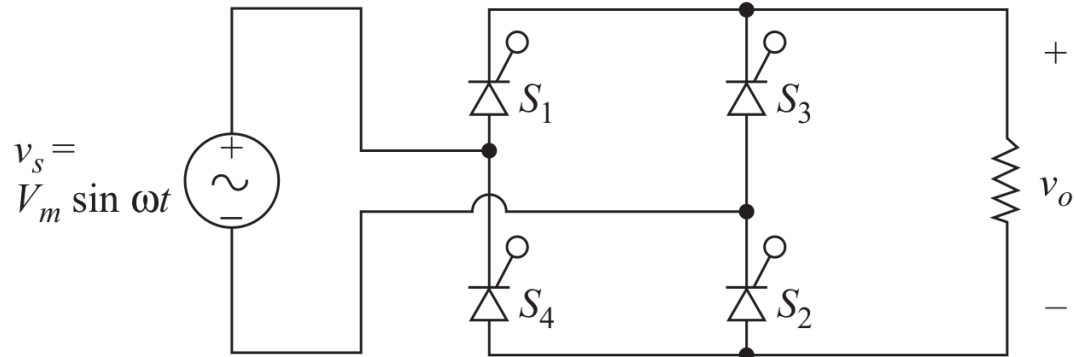
What about PF, DPF?

Real Power, Apparent Power

Real Power, Apparent Power

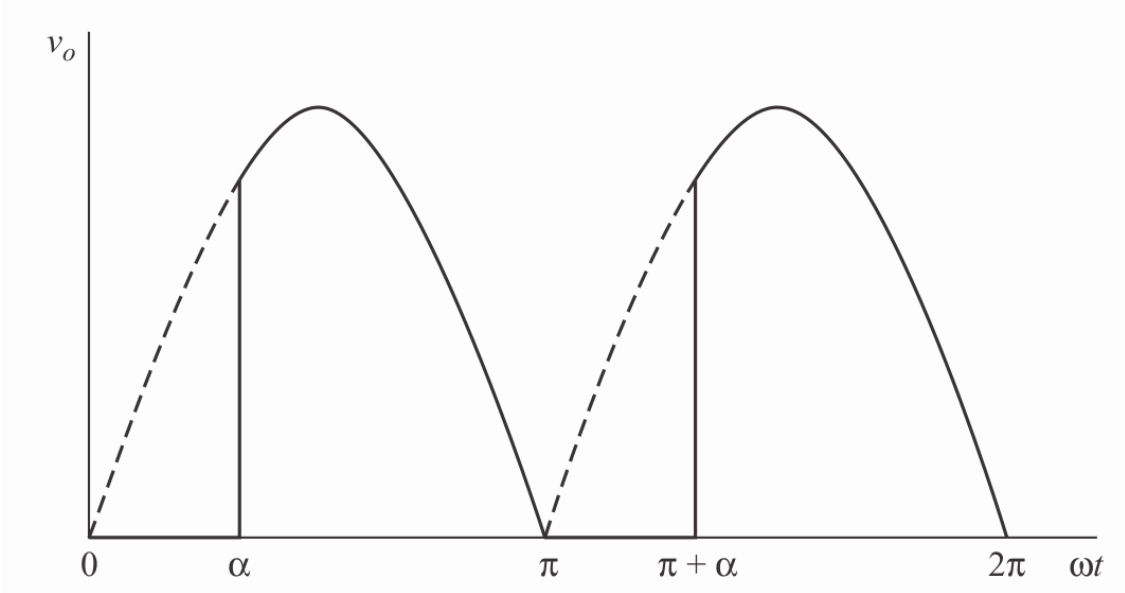


Single Phase Rectifier with Resistive Load

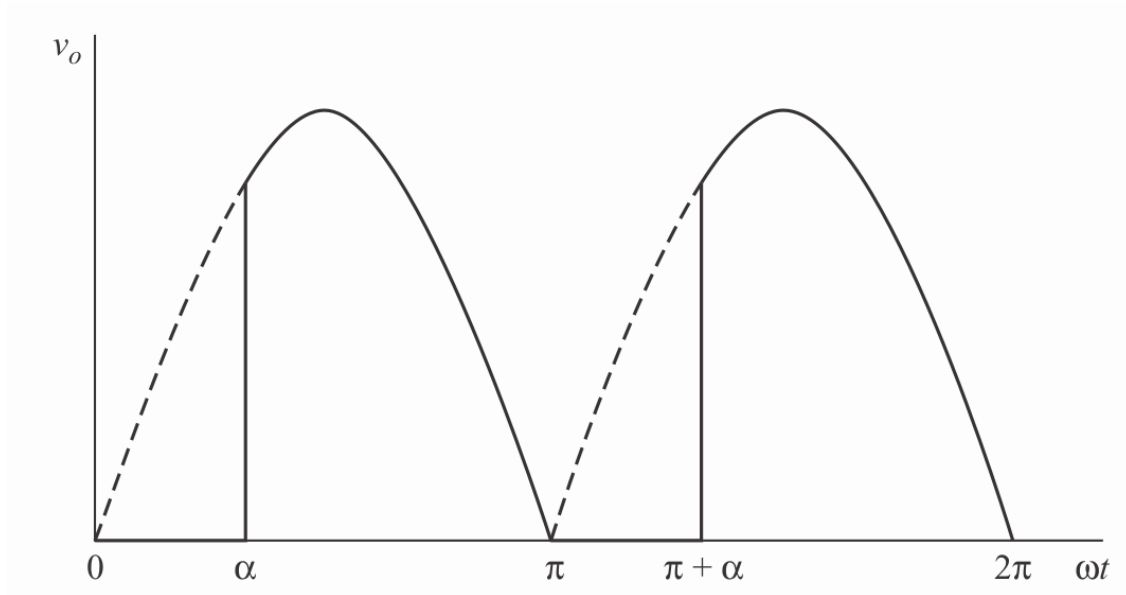


Voltage Waveform?

Single Phase Rectifier with Resistive Load

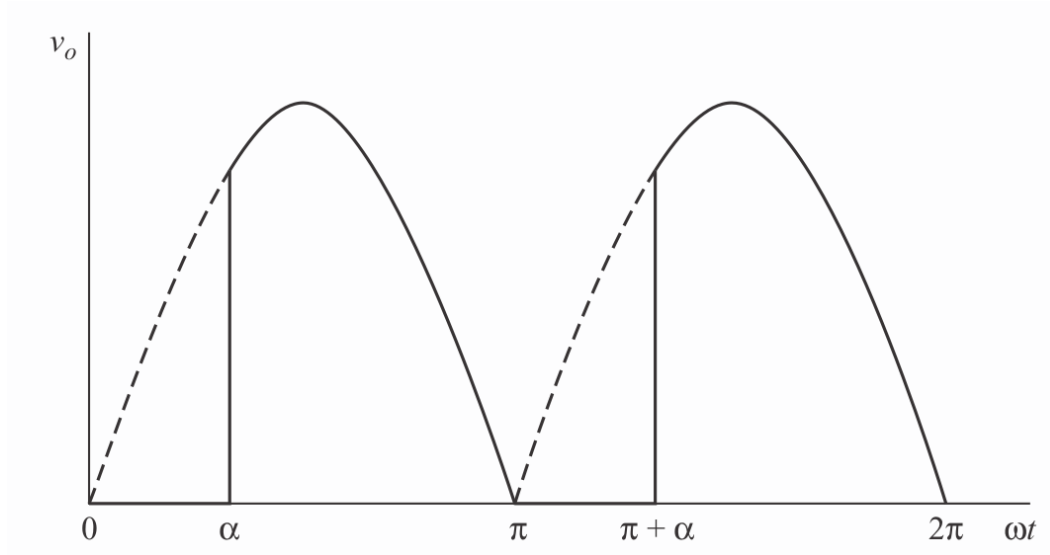


Single Phase Rectifier with Resistive Load



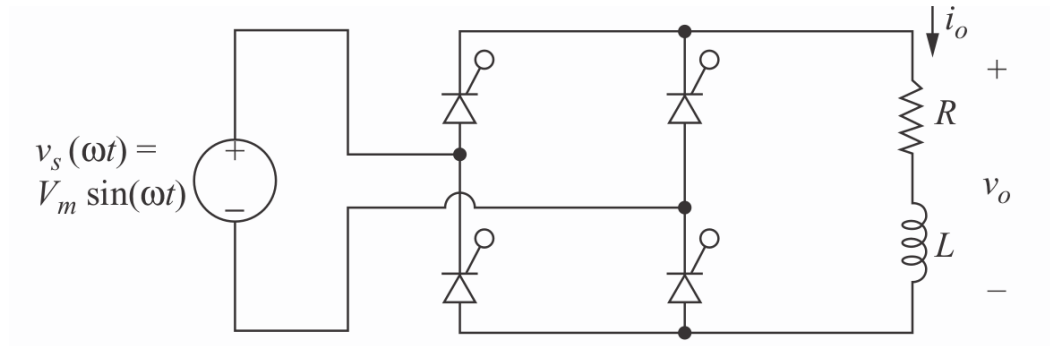
Average Voltage?

Single Phase Rectifier with Resistive Load

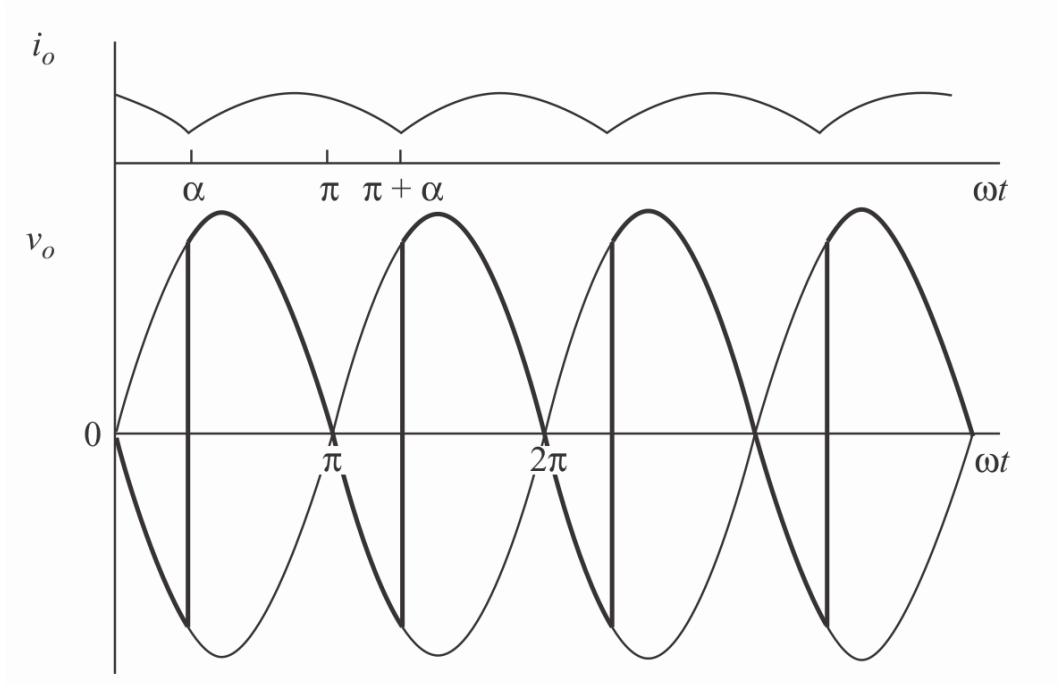


$$Vd_{\alpha} = \frac{\sqrt{2}V_s}{\pi} (1 + \cos(\alpha))$$

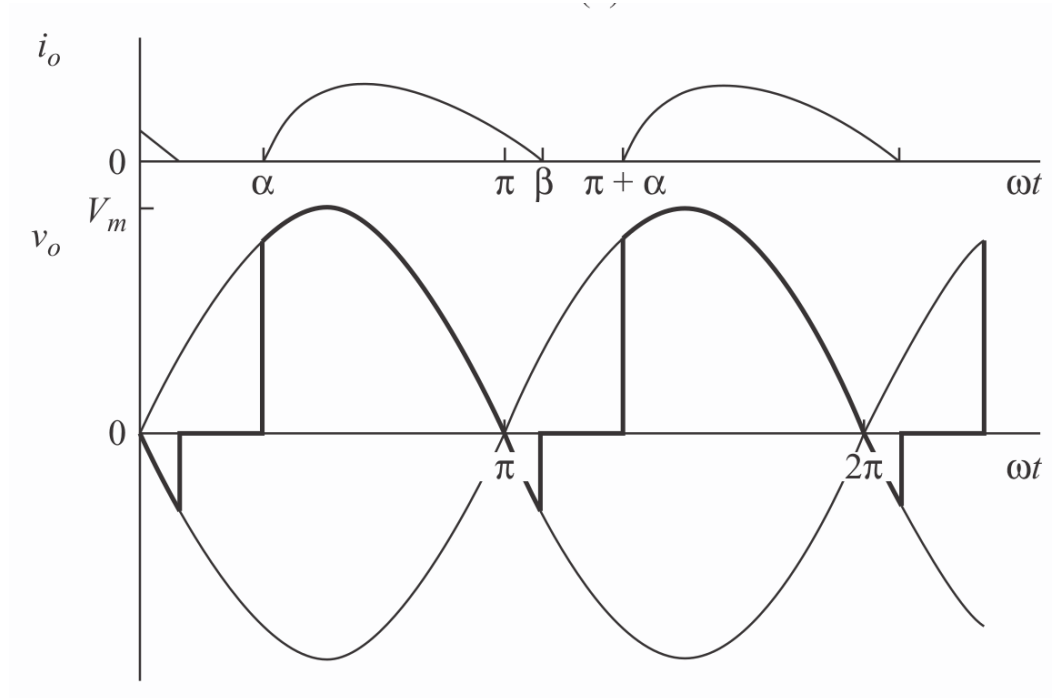
Single Phase Rectifier with R-L Load (Continuous Current)



Single Phase Rectifier with R-L Load (Continuous Current)

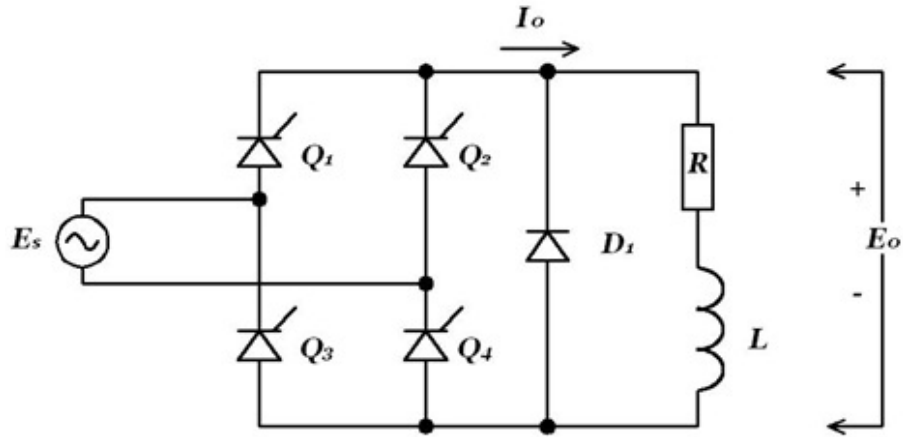


Single Phase Rectifier with R-L Load (Discontinuous Current)



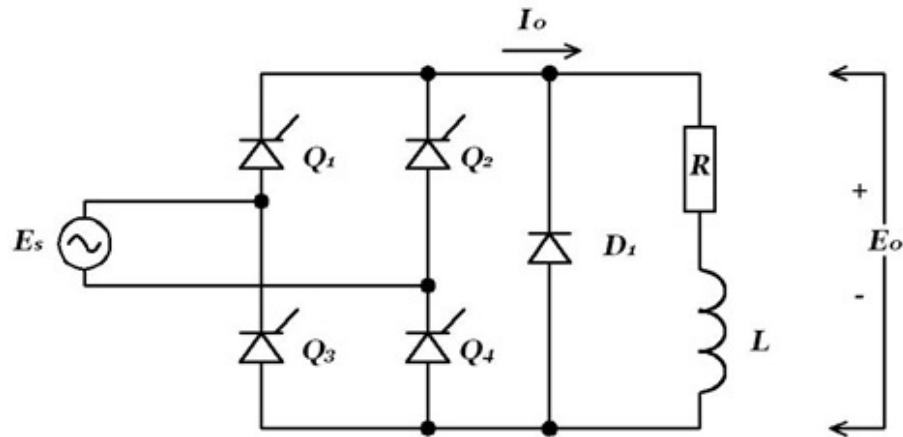
Single Phase Rectifier with Freewheeling Diode

Single Phase Rectifier with Freewheeling Diode



Can you plot the voltage, current waveform?

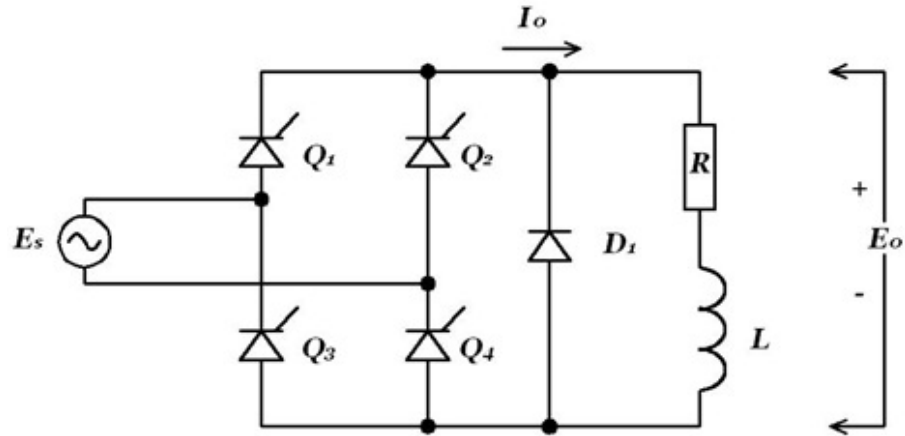
Single Phase Rectifier with Freewheeling Diode



Can you plot the voltage, current waveform?

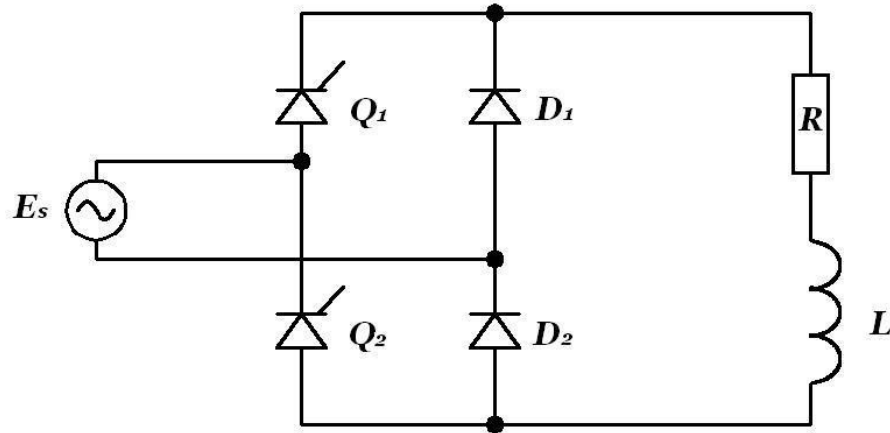
What are the advantages, disadvantages?

How can you make this circuit cheaper?



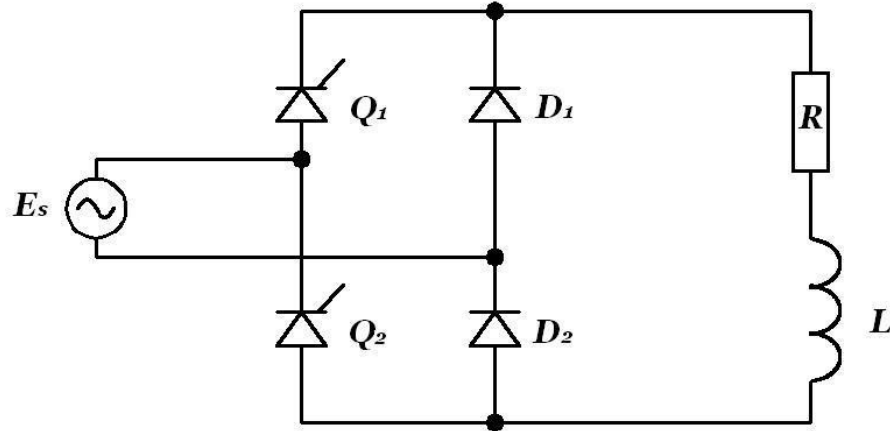
Full Bridge Half Controlled Rectifier

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D_1, D_2 works as freewheeling diodes

Full Bridge Half Controlled Rectifier

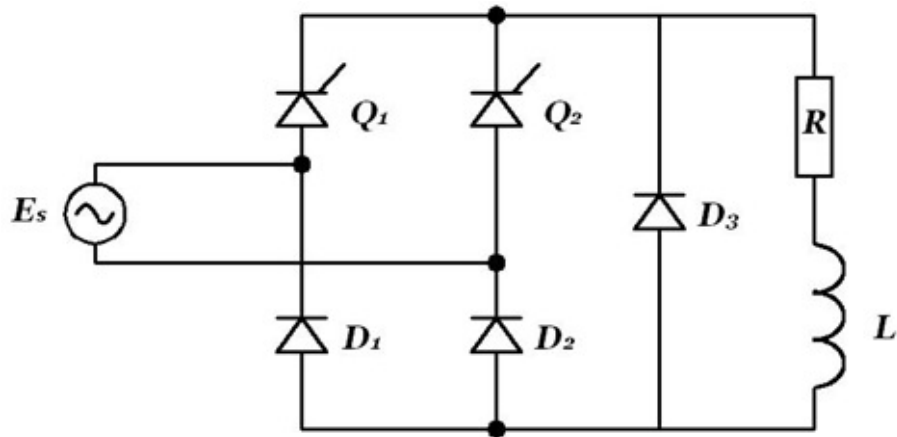


D_1, D_2 works as freewheeling diodes

V_d cannot be negative

Full Bridge Half Controlled Rectifier

Alternative (Same Output)



D_3 can be removed (depending on load, and thyristor gate signals)

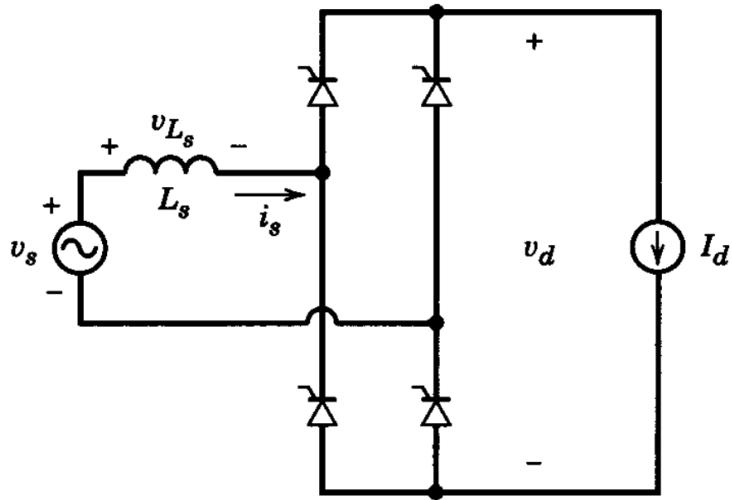
Commutation

Commutation

With source side inductance (L_s)

Commutation

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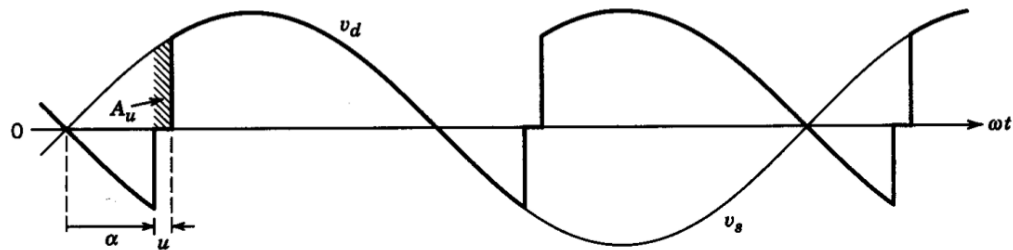
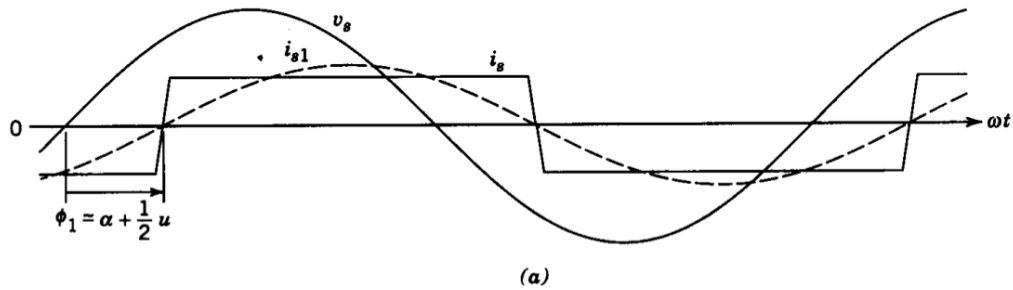
Commutation

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Can you plot the voltage and current outputs?

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Commutation

Effect on the output voltage

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$$A_u = \sqrt{2}V_s (\cos(\alpha) - \cos(\alpha + u)) = 2\omega L_s I_d$$

Commutation

Effect on the output voltage

$$A_u = \sqrt{2}V_s(\cos(\alpha) - \cos(\alpha + u)) = 2\omega L_s I_d$$

$$\cos(\alpha + u) = \cos(\alpha) - \frac{2\omega L_s I_d}{\sqrt{2}V_s}$$

Commutation

Voltage drop due to commutation

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Voltage drop due to commutation

$$\Delta V_{du} = \frac{A_u}{\pi} = \frac{2\omega L_s I_d}{\pi}$$

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Voltage drop due to commutation

$$\Delta V_{du} = \frac{A_u}{\pi} = \frac{2\omega L_s I_d}{\pi}$$

$$V_d = 0.9V_s \cos(\alpha) - \frac{2\omega L_s I_d}{\pi}$$

Example

Mohan Ex. 6.1

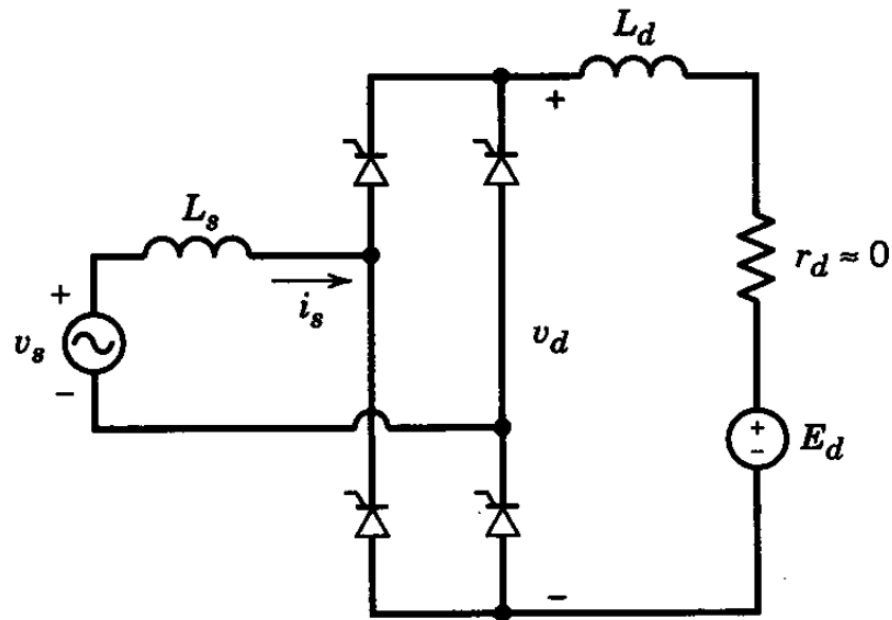
Practical Thyristor Converter

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Consider a case as a DC motor drive

Practical Thyristor Converter

Consider a case as a DC motor drive

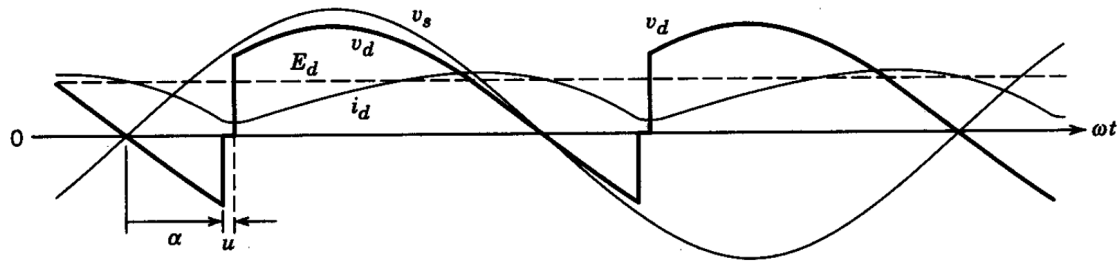


Practical Thyristor Converter

Continuous Conduction (i_d is always > 0)

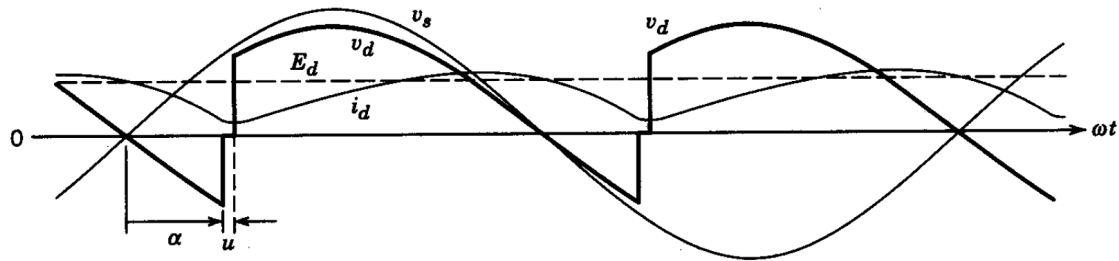
Practical Thyristor Converter

Continuous Conduction (i_d is always > 0)



Practical Thyristor Converter

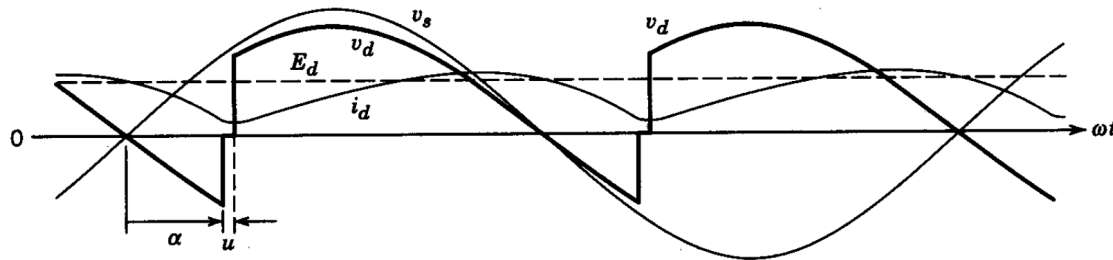
Continuous Conduction (i_d is always > 0)



Average voltage with commutation?

Practical Thyristor Converter

Continuous Conduction (i_d is always > 0)

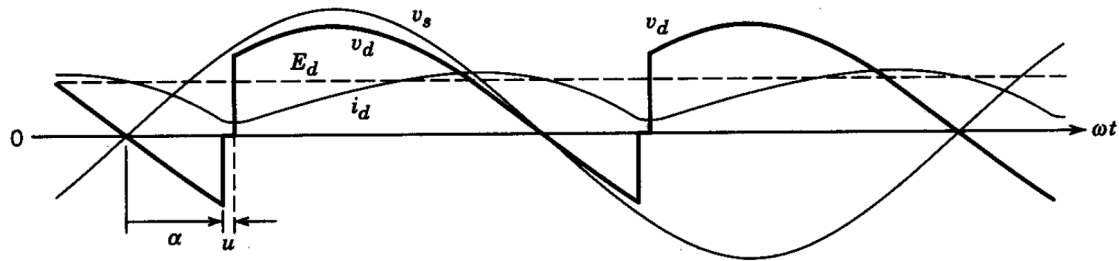


Average voltage with commutation?

$$V_d \approx 0.9V_s \cos(\alpha) - \frac{2\omega L_s I_{d,min}}{\pi}$$

Practical Thyristor Converter

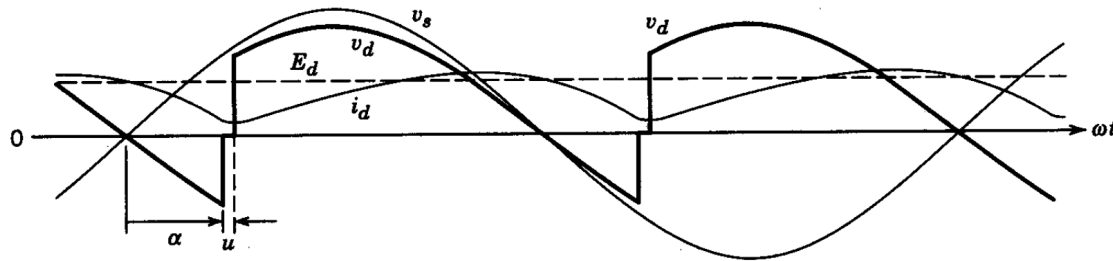
Continuous Conduction (i_d is always > 0)



Average Current?

Practical Thyristor Converter

Continuous Conduction (i_d is always > 0)



Average Current?

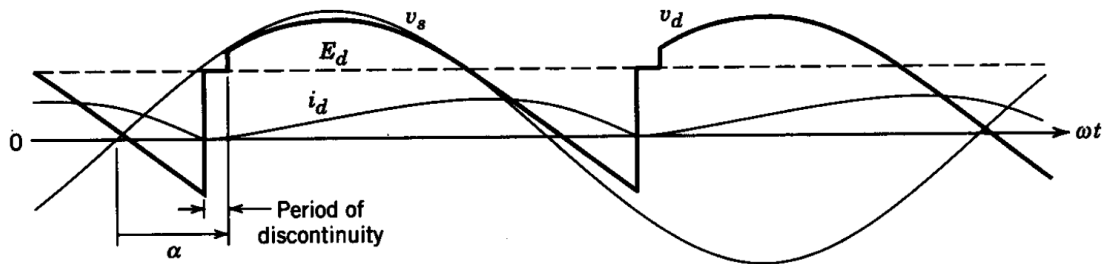
$$I_d = \frac{V_d - E_d}{r_d}$$

Practical Thyristor Converter

What happens if I_d is small?

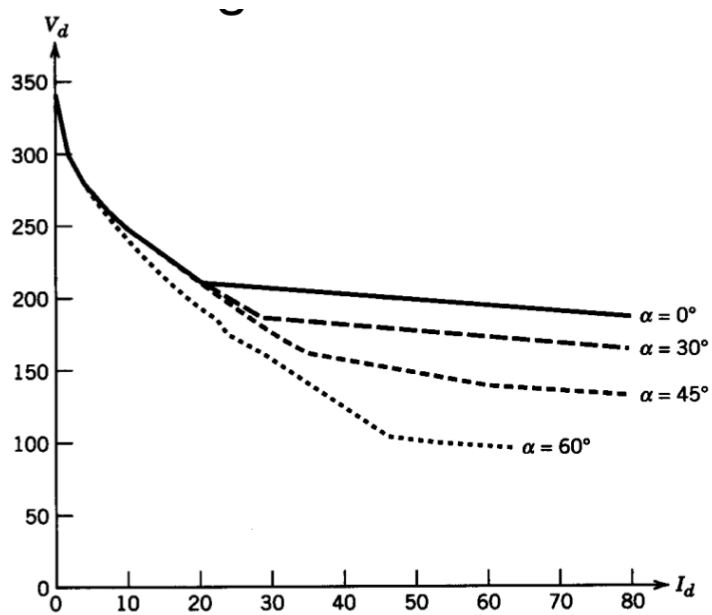
Practical Thyristor Converter

Discontinuous Conduction



Practical Thyristor Converter

Discontinuous Conduction



Inverter Mode

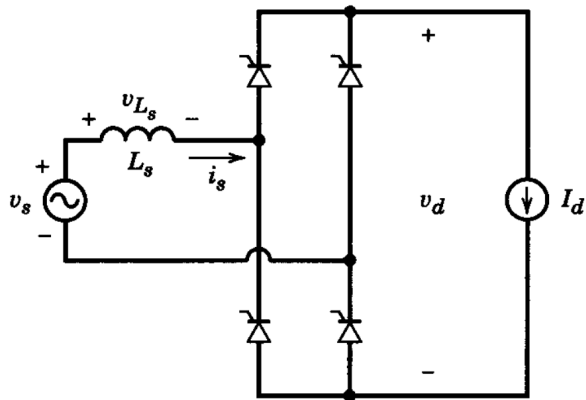
Inverter Mode

$90 < \text{Firing Angle} < 180$

Inverter Mode

$90 < \text{Firing Angle} < 180$

Average power < 0 (Power flows from DC to AC)



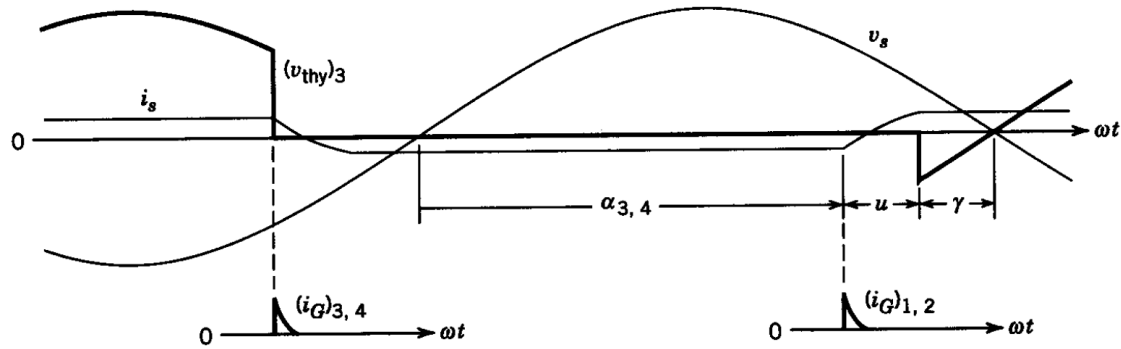
Only with active power source on DC side

Inverter Mode

Thyristor Voltage

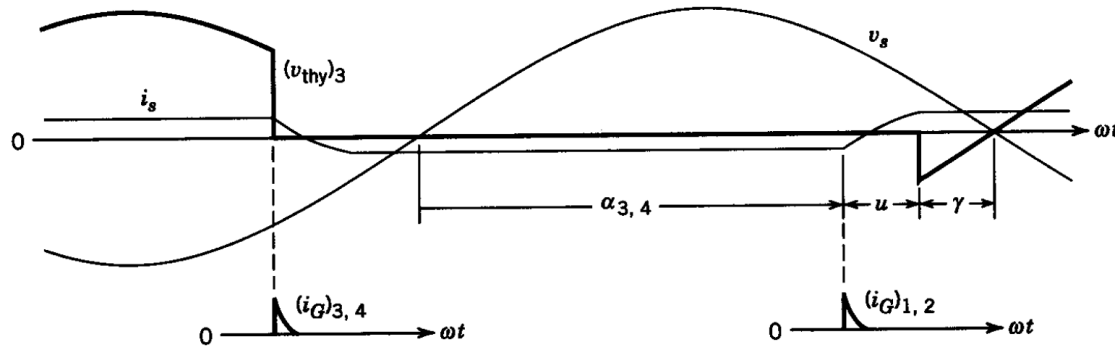
Inverter Mode

Thyristor Voltage



Inverter Mode

Thyristor Voltage



$$\text{Extinction Angle } (\gamma = 180 - (\alpha + u))$$

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