

$$S^2 = \mathbb{D} \dot{\mathbb{D}} / z \sim \phi(z) = \frac{1}{z}, \quad z \neq 0 \quad -\frac{1}{z^2}$$

$$T^* S^2 = T^* \mathbb{D} \dot{\mathbb{D}} / (z, w) \sim \left(\phi|_H, \overbrace{D\phi|_z} \right) (w)$$

$$(z, w) \in T^* \mathbb{D}, \quad z \neq 0$$

$$\begin{aligned} &= \mathbb{D} \times \mathbb{D} \dot{\mathbb{D}} / \mathbb{D} \times \mathbb{D} / (z, w) \sim \left(\frac{1}{z}, -\frac{1}{z^2} \cdot w \right) \\ & \quad z \neq 0 \end{aligned}$$

$$\underline{\text{Ex}} \quad S^4 = \mathbb{H}\mathbb{R}^4 / \mathbb{P} \sim \frac{\mathbb{H}}{\mathbb{P}}, \quad \mathbb{P} \neq \emptyset$$

$$\mathbb{H} = \mathbb{R}^4, \quad \mathbb{P} = (x_1, x_2, x_3, x_4) = x_1 + i x_2 + j x_3 + k x_4$$

$$\bar{\mathbb{P}} = x_1 - i x_2 - j x_3 - k x_4$$

$$\mathbb{P}\bar{\mathbb{P}} = x_1^2 + x_2^2 + x_3^2 + x_4^2 \Rightarrow \mathbb{P} \frac{\bar{\mathbb{P}}}{\|\mathbb{P}\|} = 1, \quad \mathbb{P} \neq \emptyset.$$

$$\mathbb{P}^{-1} = \frac{1}{\mathbb{P}} = \frac{\bar{\mathbb{P}}}{\|\mathbb{P}\|}.$$

$$T_x S^4 = T_x \mathbb{H} \cup T_x \mathbb{H} / (\mathbb{R}v) \sim \left(\frac{1}{p}, D\phi(p)(v) \right)$$

$$\phi: \mathbb{H}^* \rightarrow \mathbb{H}^*, \quad \phi(p) = \frac{1}{p}, \quad p \in \mathbb{H}^*$$

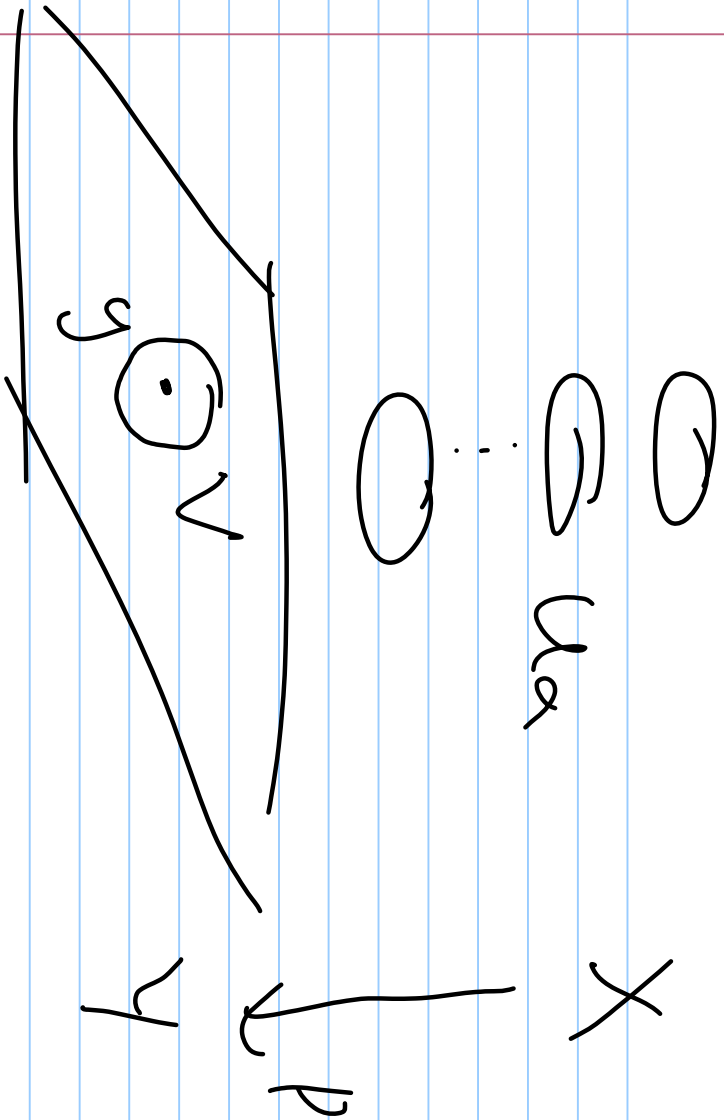
$$D\phi(p)(v) = -\frac{1}{p} v \frac{1}{p}$$

Quotient Manifolds:

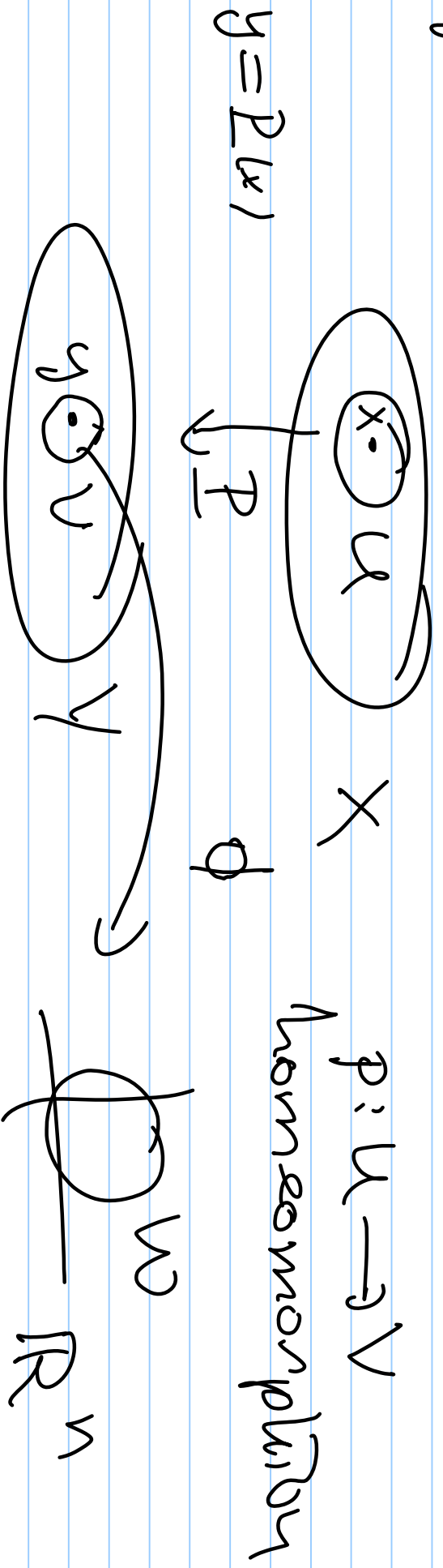
X, Y topological spaces, $p: X \rightarrow Y$ cont. map.
 P is called a covering space if for any
 $y \in Y$ there is a neighborhood V of Y with

(i) $y \in V$

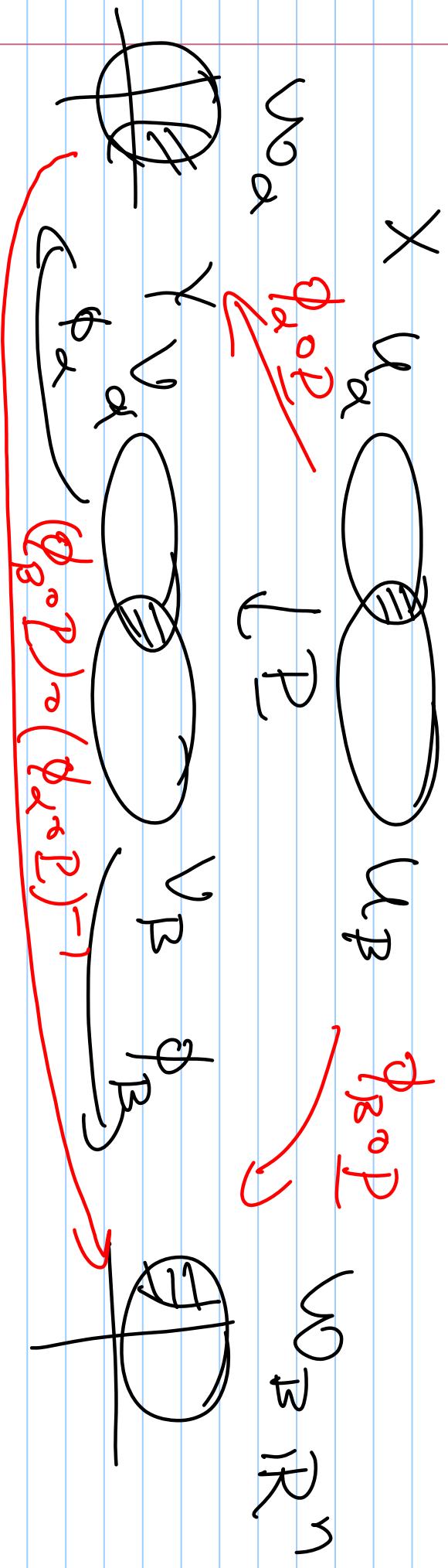
(ii) $p^{-1}(V)$ is a disjoint union of open subsets
 $\sum U_\alpha$ of X , where for each α the restriction,
map $p: U_\alpha \rightarrow V$ is a homeomorphism.



If Y has a smooth structure then X gets a smooth structure as follows:



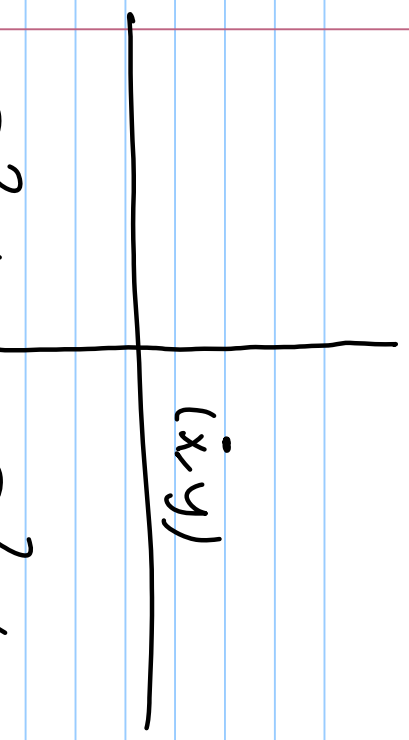
The $\phi \circ P: U \rightarrow W$ is a coordinate system about $x \in X$.



$$\begin{aligned}(\phi_{\mathbb{R}^n} \circ \mathcal{D}) \circ (\phi_{\mathcal{A}} \circ \mathcal{P})^{-1} &= \phi_{\mathbb{R}^n} \circ \underbrace{(\mathcal{P} \circ \mathcal{D}^{-1})}_{\text{linear}} \circ \phi_{\mathcal{A}}^{-1} \\ &= \phi_{\mathbb{R}^n} \circ \phi_{\mathcal{A}}^{-1} \stackrel{\text{linear}}{=} \phi_{\mathcal{A}}^{-1} \in C^\infty, \text{ because}\end{aligned}$$

Y has smooth structure.

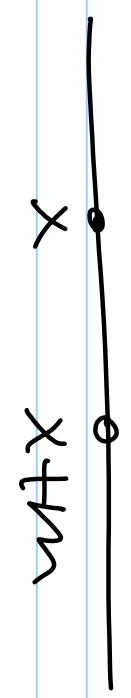
$$\begin{aligned}\text{Ex: } G &= \mathcal{Z} \times \mathcal{Z}, \quad G \times \mathbb{R}^2 \longrightarrow \mathbb{R}^2 \\ (m, n) \cdot (x, y) &= (x+m, y+n)\end{aligned}$$



$(x+m, y+n)$

$(m, n) \in G = \mathbb{Z} \times \mathbb{Z}$

$$\mathbb{R}^2 / G = \mathbb{R}^2 / \mathbb{Z} \times \mathbb{Z} = \mathbb{R} / \mathbb{Z} \times \mathbb{R} / \mathbb{Z} = \mathbb{S}^1 \times \mathbb{S}^1$$



$$\mathbb{R}^2 \simeq [0, 1] \times [0, 1] / \sim = S^1$$

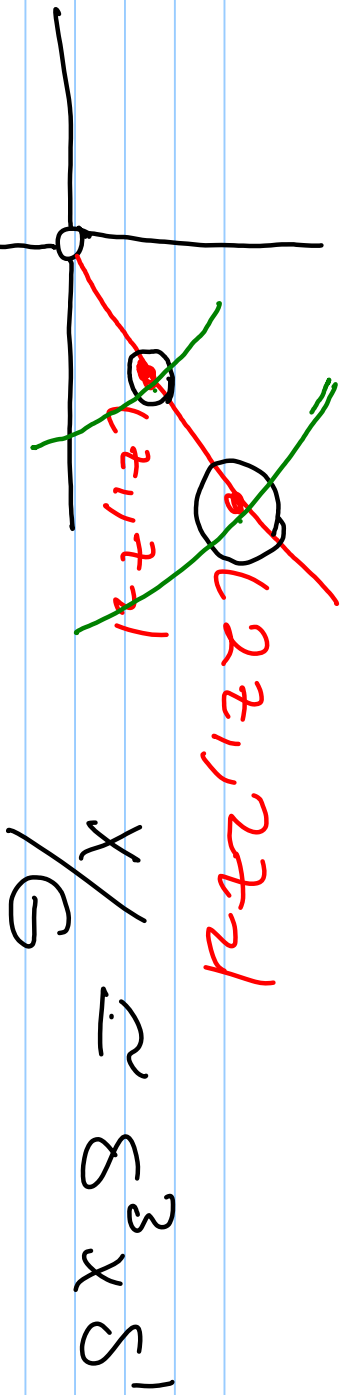
$$h: \mathbb{R} \longrightarrow S^1, \quad h(t) = (\cos 2\pi t, \sin 2\pi t)$$

$$h(t) = h(t+m) \text{ and}$$

$$h(t_1) = h(t_2) \text{ implies } t_1 - t_2 \in \mathbb{Z}.$$

$$2) \quad G = \mathbb{Z}, \quad X = \mathbb{D}^2 \setminus \{(0, 0)\}$$

$$G \times X \longrightarrow X, \quad n \cdot (z_1, z_2) = (2^n z_1, 2^n z_2)$$



$$D^2 \{(0,0)\} / \mathbb{Z} \longrightarrow S^3 \times S^1$$

$$(z_1, z_2) \longmapsto \left(\frac{(z_1, z_2)}{\|(z_1, z_2)\|}, e^{2\pi i \log_2 \|(z_1, z_2)\|} \right)$$

diffeomorphism.

Rank Theorems:

Definition: Let $f: M \rightarrow N$ be a smooth map of smooth manifolds and $p \in M$.

Let $Df(p): T_p M \rightarrow T_p N$ is injective

then we say that f is an immersion at p . If $Df(p): T_p M \rightarrow T_p N$ is onto then we say that f is an submersion at p .

$$\underline{\text{Ex}}: m \leq n, f: \mathbb{R}^m \rightarrow \mathbb{R}^n, \quad n-m$$

$$(x_1, \dots, x_m) \mapsto (x_1, \dots, x_m, \overbrace{0, \dots, 0}^{n-m})$$

$$Df(p): \overline{T_p} \mathbb{R}^m \rightarrow \mathbb{R}^n, \quad v = (v_1, \dots, v_m) \in \overline{T_p} \mathbb{R}^m$$

$$Df(p)(v) = (v_1, \dots, v_m, 0, \dots, 0) \text{ is clearly } 1-1.$$

This is called the canonical immersion.

Let $m \geq n$, $g: \mathbb{R}^m \rightarrow \mathbb{R}^n$, $g(x_1, \dots, x_m) = (x_1, \dots, x_n)$.

Clearly, $Dg(p): T_p \mathbb{R}^m \rightarrow T_{g(p)} \mathbb{R}^n$ is given by

$Dg(p)(v_1, \dots, v_m) = (v_1, \dots, v_n)$. So $Dg(p)$ is clearly onto and thus g is an submersion, called the canonical submersion.

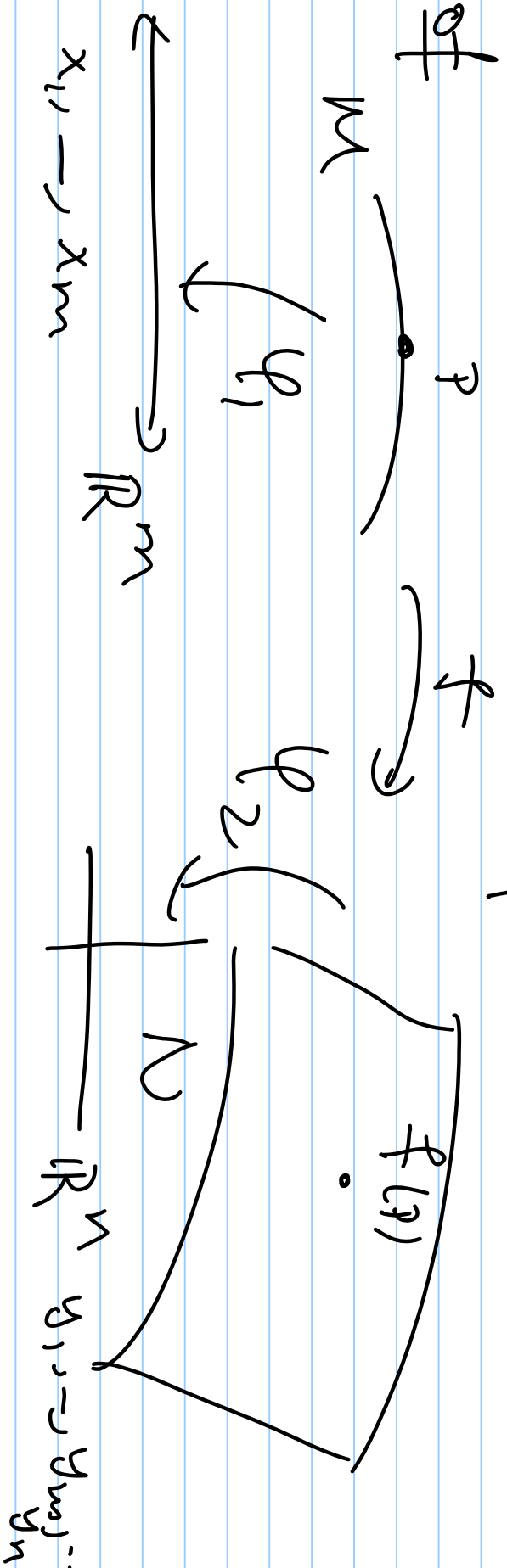
Theorem: Let $f: M \rightarrow \mathbb{D}$ be a smooth map and $p \in M$ so that f is an immersion at p . Then one can find coordinate charts around p and $f(p)$, say $\varphi_1: U_1 \rightarrow V_1$, $\varphi_2: U_2 \rightarrow V_2$, $p_1 \in U_1 \subseteq M$, $f(p) \in U_2 \subseteq N$, $V_1 \subseteq \mathbb{R}^m$, $V_2 \subseteq \mathbb{R}^n$, so that

$$\begin{array}{ccc}
 U_1 \circlearrowleft & \xrightarrow{f} & U_2 \circlearrowleft \\
 \varphi_1 \swarrow & & \searrow \varphi_2 \\
 \mathbb{R}^m \supseteq V_1 \circlearrowleft & \xrightarrow{\varphi_2 \circ f \circ \varphi_1^{-1}} & V_2 \circlearrowleft \subseteq \mathbb{R}^n
 \end{array}$$

$$(\varphi_2 \circ f \circ \varphi_1^{-1})(x_1, \dots, x_m) = (x_1, \dots, x_m, 0, \dots, 0).$$

Smoker statement holds for submersions.

Proof



$Df(p) : T_p M \rightarrow T_p N$ is injective

$$Df(p) =$$

$$\begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \dots & \frac{\partial f_1}{\partial x_m} \\ \vdots & & \vdots \\ \frac{\partial f_m}{\partial x_1} & \dots & \frac{\partial f_m}{\partial x_m} \\ \vdots & & \vdots \\ \frac{\partial f_n}{\partial x_1} & \dots & \frac{\partial f_n}{\partial x_m} \end{bmatrix} \quad n \times m$$

$$f = (f_1, \dots, f_n)$$

$$f_i = f_i(x_1, \dots, x_m)$$

Assume that the first m -rows of $Df(p)$ are linearly independent,

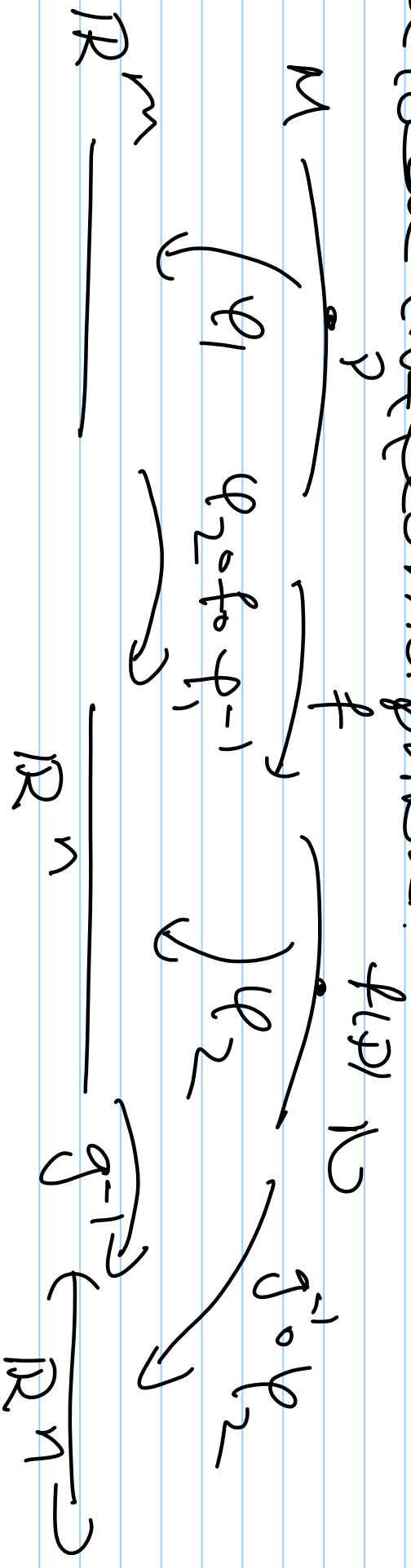
Let $g: \mathbb{R}^m \times \mathbb{R}^{n-m} \rightarrow \mathbb{R}^n$ be given by

$$g(x_1, \dots, x_m, x_{m+1}, \dots, x_n) = f(x_1, \dots, x_m) + (0, \dots, 0, x_{m+1}, \dots, x_n)$$

$$Dg(p) = \begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \dots & \frac{\partial f_1}{\partial x_m} & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & 0 & \dots & 0 \\ \frac{\partial f_m}{\partial x_1} & \dots & \frac{\partial f_m}{\partial x_m} & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & 1 & \dots & 0 \\ \vdots & \vdots & \vdots & 0 & \dots & 1 \end{bmatrix} = \begin{bmatrix} f_1 & f_2 & \dots & f_m & f_{m+1} & \dots & f_n \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \end{bmatrix}$$

Now Dg is invertible, $g: \mathbb{R}^m \times \mathbb{R}^{n-m} \rightarrow \mathbb{R}^n$.

So by the Inverse function theorem g is a local diffeomorphism.



$(x_1, \dots, x_m) \mapsto (f_1, \dots, f_n) \mapsto g^{-1}(f_1, \dots, f_n)$, where

$(x_1, \dots, x_m, x_{m+1}, \dots, x_n) \mapsto (f_1, \dots, f_n)$
 $(f_1, \dots, f_n) \mapsto (f_{m+1}, f_{m+2}, \dots, f_n, x_1, \dots, x_m)$



Claim: $g^{-1}(f_1(x_1, \dots, x_n), \dots, f_n(x_1, \dots, x_n)) = (x_1, \dots, x_m, \theta, \dots, \theta)$

Because, $g(x_1, \dots, x_m, \theta, \dots, \theta) = (f_1, \dots, f_n)$.