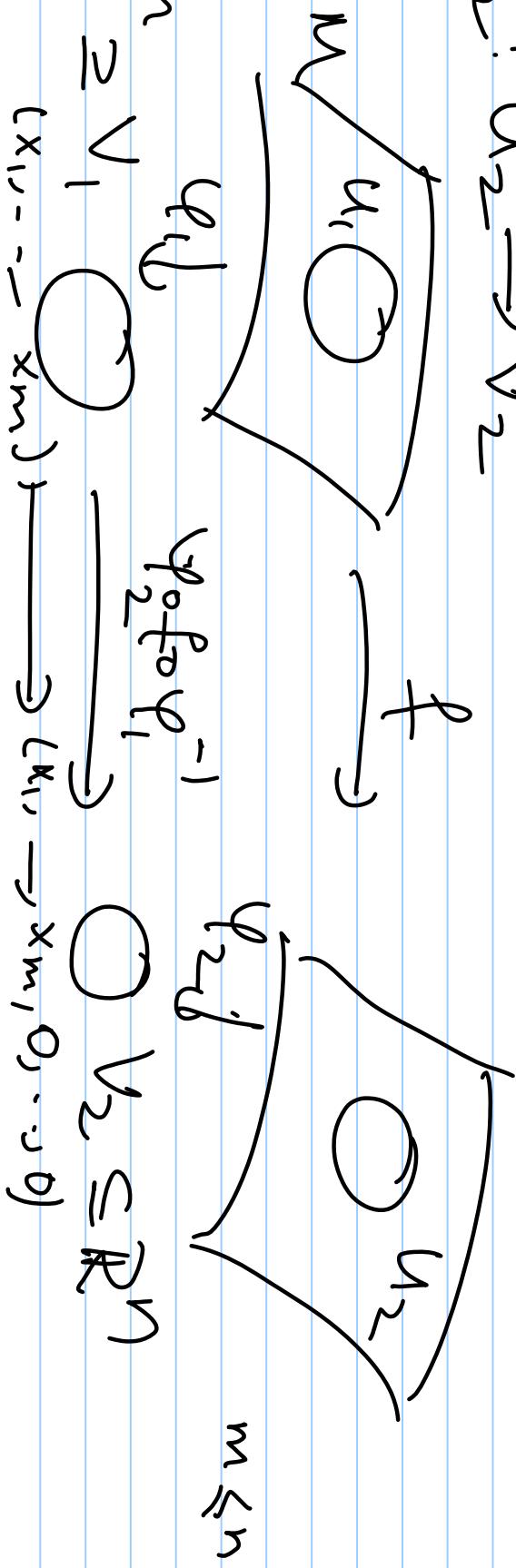


$f: M \rightarrow N$ immersion at a point $p \in M$
 $\rho \in U_1 \subseteq M$, $f(p) \in U_2 \subseteq N$, $\varphi_i: V_i \rightarrow V_1$
 $\varphi_2: V_2 \rightarrow V_2$

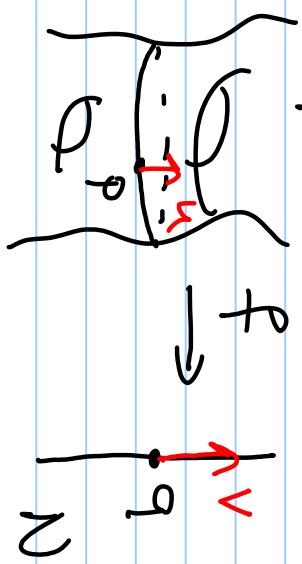


If f is a submersion then φ_i 's can be chosen so that

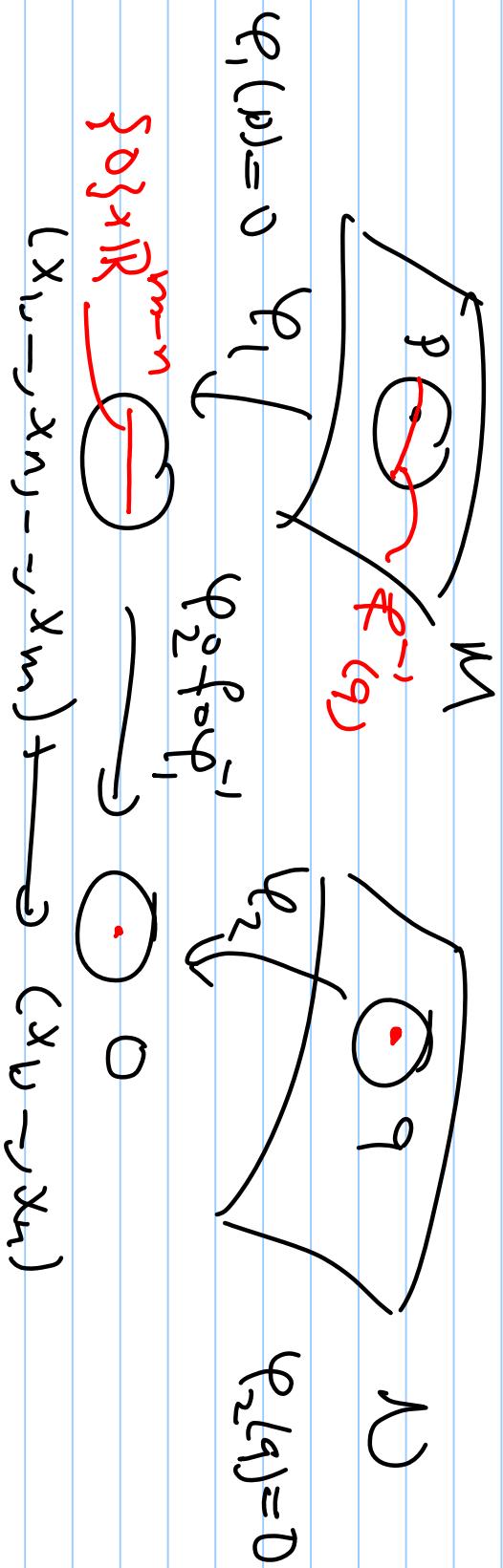
$\varphi_2 \circ \varphi_i^{-1}$ becomes standard submersion.

$$\varphi_n \circ \varphi_1^{-1}(x_1, \dots, x_n, \dots, x_m) = (x_1, \dots, x_n) \quad (m \geq n).$$

Definition: $f: M \rightarrow N$ smooth map. A point $q \in N$ is called a regular value of $Df(p): T_p M \rightarrow T_q N$ if for all $p \in f^{-1}(q)$.



In this case, since $Df(p): T_p M \rightarrow T_{f(p)} N$ is an isomorphism at $p \in M$ and in some coordinate systems



$$\begin{aligned} \text{So, } f^{-1}(q) \text{ becomes in the coordinate system} \\ \varphi_1(f^{-1}(q)) &= \left\{ (x_1, \dots, x_n) \in \mathbb{R}^m \mid x_1 = \dots = x_n = 0 \right\} \\ &= \{0\} \times \mathbb{R}^{m-n} \end{aligned}$$

This implies that $f^{-1}(q)$ is an $m-n$ -dimensional submanifold of M .

Example: $\oplus : M(n,n) \rightarrow S(n)$, $\oplus(Q) = Q^T Q$
 $M(n,n) = \mathbb{R}^{n \times n} = \mathbb{R}^{n^2}$: the set of all $n \times n$ -real matrices
 $S(n) = \{ A \in M(n,n) \mid A^T = A \}$, the set of all

$n \times n$ -symmetric real matrices.

$$S(n) = \left\{ \begin{bmatrix} a_{ij} \end{bmatrix}_{n \times n} \mid a_{ij}^* = a_{ji}, \forall i, j \right\}$$
$$= \mathbb{R}^{\frac{n(n+1)}{2}}$$

$$\Phi : M(n, n) \rightarrow S(n), Q \mapsto Q^T Q.$$

$$D(\mathbb{I}^n) : T_{\mathbb{I}^n} M(n, n) \rightarrow T_{\mathbb{I}^n} S(n)$$

$$M(n, n) \stackrel{''}{=} S(n)$$

$$A \xrightarrow{\quad} A + A^T$$

$$1 + 2 + \dots + n = \frac{n(n+1)}{2}$$

$$\begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{bmatrix}$$

$D\hat{\Phi}$ is onto: If $Q \in S(n)$, then $Q = \frac{Q}{2} + \frac{Q^T}{2} = D\hat{\Phi}(I_d)\left(\frac{Q}{2}\right)$.

Hence, $I_d \in S(n)$ is a regular value of $\hat{\Phi}$.

Therefore, $\hat{\Phi}^{-1}(I_d)$ is a smooth submanifold of $M(n, \mathbb{R})$.

of dimension $\dim M(n, \mathbb{R}) - \dim \{I_d\} = n^2 - \frac{n(n+1)}{2} = \frac{n(n-1)}{2}$.

Moreover,

$$\hat{\Phi}^{-1}(I_d) = \left\{ Q \in M(n, \mathbb{R}) \mid Q^T Q = I_d \right\}$$

$= O(n)$ the set of $n \times n$ orthogonal real matrices.

Sard's Theorem: $\Omega \subseteq \mathbb{R}^n$ open subset, $F: \Omega \rightarrow \mathbb{R}^m$ smooth

map. Let $C \subseteq \Omega$ be the set of all critical points of

$F: C = \{p \in \Omega \mid DF(p): T_p \Omega \rightarrow T_{F(p)} \mathbb{R}^m \text{ is not onto}\}$.

Then the $F(C)$ has measure zero in \mathbb{R}^m .

Ex: $n < m$, $Df(p): T_p \Omega \xrightarrow{\text{is}} T_{f(p)} \mathbb{R}^m$ cannot be onto

$$\mathbb{R}^n \xrightarrow{\text{is}} \mathbb{R}^m$$

Hence, the set of critical points C of F in Ω is Ω . So by Sard's Theorem $F(C)$, the set of critical values of F has measure zero, so the image $F(\Omega)$ has

measure zero.

An application of Sard's Theorem: Embedding of smooth manifolds into Euclidean spaces.

Theorem: Let M be a smooth n -dimensional manifold. Then there is an immersion of M into \mathbb{R}^{2n} and an embedding into \mathbb{R}^{2n+1} .

Proof: First embed M into \mathbb{R}^N for some big N .

M compact $\Rightarrow \exists V \subseteq M, \varphi: V \rightarrow V \subseteq \mathbb{R}^N$

$$M = U_1 \cup \dots \cup U_k \rightarrow \varphi_i : U_i \rightarrow V_i \subseteq \mathbb{R}^n$$

Extend φ_i to all M as a smooth function.

$$\begin{matrix} M & \longrightarrow & \mathbb{R}^n \times \mathbb{R}^n \times \dots \times \mathbb{R}^n = \mathbb{R}^{nk} \\ p & \longmapsto & (\varphi_1(p), \varphi_2(p), \dots, \varphi_k(p)) \end{matrix}$$

To map this map onto one to one we choose for each i a smooth function $p_i : M \rightarrow [0, 1]$ so that it takes the value 1 in an open set in U_i containing p .

$$w_i \subset \overline{U_i} \subset U_i$$
$$p_i \equiv 1 \quad M = \cup U_i$$

Then the map $F: M \rightarrow \mathbb{R}^N$

$$F = (\varphi_1, \dots, \varphi_k, \varphi_1, \varphi_2, \dots, \varphi_k) \rightarrow \text{a 1-1 immersion.}$$

Moreover, M is compact and thus any H^1 immersion N on

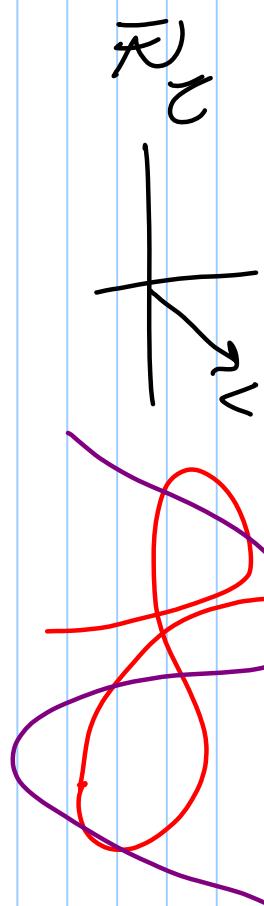
embedding.

So we may assume M is a submanifold of some \mathbb{R}^N .
Assume that $N \geq 2n+1$. Consider the function

$$\psi_1: M \times M \times \mathbb{R} \rightarrow \mathbb{R}^N, (x_1, x_2, \lambda) \mapsto x_1(x_1 - x_2) \text{ and}$$

$$\psi_2: T_x M \rightarrow \mathbb{R}^N, (x, v) \mapsto v, (x, v) \in T_x M \subseteq T_x \mathbb{R}^N \subseteq \mathbb{R}^N$$

$N \geq 2^{n+1} \geq 2^n$ and thus $\text{Im } \psi_1$ and $\text{Im } \psi_2$ consist of critical values of ψ_1 and ψ_2 respectively. In particular, ψ_1 and ψ_2 have measure zero. Since any ball in \mathbb{R}^N has positive measure there is some vector $v \in \mathbb{R}^N$, $v \neq 0$, not contained in the image of ψ_1 and ψ_2 .



Let T_V be the hypersurface in \mathbb{R}^n perpendicular to the vector v .

$$\mathbb{R}^{n-1} \cong T_V \xrightarrow{*} V$$

Let $\pi: \mathbb{R}^n \rightarrow T_V \cong \mathbb{R}^{n-1}$ be the orthogonal projection.

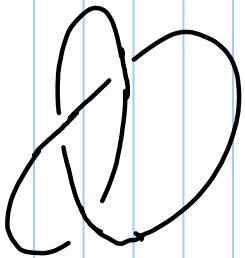
Claim: The composition

$$\pi \circ F: M \rightarrow T_V \cong \mathbb{R}^{n-1}$$

is still a one-to-one immersion.
Proof Exercise.

This finishes the proof. \blacksquare

\mathbb{H}^2



$$\mathbb{H}^2 \times S^3 = \mathbb{S}^2 \setminus \{(0,0)\} / (z_1, z_2) \sim (2z_1, 2z_2)$$

$$R^2 \times R^4 = R^6$$

$S^1 \times S^3 + S^{10}$ is a complex submanifold. ($S^1 \times S^3$ compact)

$S^1 \times S^3 \neq \mathbb{CP}^N$ as a complex manifold.

(Homology of $S^1 \times S^3$ is not suitable)

Differential Forms: $U \subseteq \mathbb{R}^n$ open subset

$p \in U$, $T_p U$ tangent space: $T_p U = \text{span} \left\{ \frac{\partial}{\partial x_1}|_p, \dots, \frac{\partial}{\partial x_n}|_p \right\}$

Cotangent space $T_p^* U = \text{dual of } T_p U$

$= \text{span} \{ dx_1|_p, \dots, dx_n|_p \}$ such that

$$dx_i(p) \left(\frac{\partial}{\partial x_j} \right)_p = \delta_{ij}, \text{ for all } i, j = 1 \dots n.$$

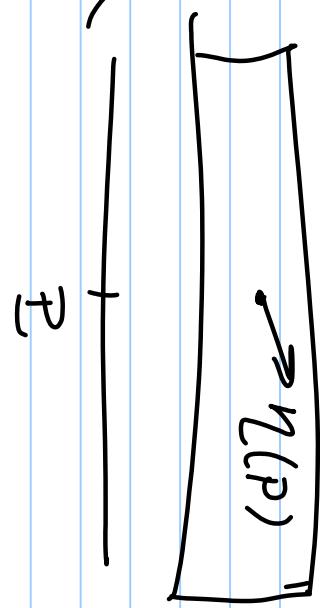
$$T^*U = \bigcup_{p \in U} T_p^*U \ni (p, \nu)$$

$$\downarrow_U$$

p

As in the case of tangent bundle the cotangent bundle is a smooth manifold of dimension $2n$ and the projection map π is smooth.

A 1-form on U is a smooth section of the map
 $\pi: T^*U \rightarrow U: \nu: U \rightarrow T^*U$ such that
 $\pi \circ \nu: U \rightarrow U$ is identity.



$$\nu(p) = a_1(p) dx_1|_p + \dots + a_n(p) dx_n|_p$$

$a_i: U \rightarrow \mathbb{R}$ smooth functions

Ex: $M = \mathbb{R}^3$, $\omega(x,y,t) = x^2y \frac{dx}{x} - 3e^x t \frac{dy}{x} dt$ is a smooth one form on \mathbb{R}^3 .

If $X(x, y, z) = x \frac{\partial}{\partial x}|_p - 2 \frac{\partial}{\partial y}|_p - y \frac{\partial}{\partial z}|_p$, then the computation

$\omega(X)|_{(x,y,z)}$ is a function on \mathbb{R}^3 given by

$$\omega(X)|_{(x,y,z)} = x^3 y + b e^x z - y$$

k -form on $U \subseteq \mathbb{R}^n$

$$dx_i = \underline{dx_i}|_p$$

$$f(p) dx_{i_1} \wedge dx_{i_2} \wedge \dots \wedge dx_{i_k}$$

In general, an k -form on U has the form

$$\omega = \sum_I f_I(p) dx_I, \quad I = (i_1, i_2, \dots, i_k) \quad 1 \leq i_j \leq n$$

$$dx_I \doteq dx_{i_1} \wedge dx_{i_2} \wedge \dots \wedge dx_{i_k}$$

Onnekk: S^2 unit sphere in \mathbb{R}^3 . Let ω be the 2-form

on S^2 given by

$$\omega(p)(u, v) \doteq (u \times v) \cdot p$$

$$u, v \in \overline{T_p S^2}$$

$$p = (x, y, z), \quad u = (u_1, u_2, u_3), \quad v = (v_1, v_2, v_3)$$

$$\omega(p)(u, v) = (u_2 v_3 - u_3 v_2, u_3 v_1 - u_1 v_3, u_1 v_2 - u_2 v_1) \cdot (x, y, z)$$

$$\Rightarrow \omega = x dy \wedge dz + y dz \wedge dx + z dx \wedge dy$$

