### **Rotational Kinetic Energy**

- Assume that a rigid body is rotating around a fixed axis with angular velocity  $\omega$ .
- $m_i$  located at a distance  $R_i$  from the axis will have a speed  $\omega R_i$ .
- The kinetic energy of  $m_i$  is  $K = \frac{1}{2}m_i(R_i\omega)^2 = \frac{1}{2}m_iR_i^2\omega^2$ .
- Summing the kinetic energy of all the masses, the kinetic energy of the rigid body is:

$$K = \sum_{i} \frac{1}{2} (m_i R_i^2) \omega^2 \equiv \frac{1}{2} I \omega^2$$

PHYS109 164 / 175

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# Kinetic Energy of A Rotating Object That also Has Translational Motion

- Let  $\vec{r}_{CM}$  be the position of the CM.
- Let  $\vec{r_i}$  and  $\vec{R_i}$  be the position of mass  $m_i$  in the rigid body relative to a fixed coordinate axis and relative to the CM respectively:  $\vec{r_i} = \vec{r_{CM}} + \vec{R_i}$
- $\vec{v}_i = \vec{v}_{CM} + \vec{V}_i$ , where  $\vec{V}_i$  is the velocity relative to the CM.
- Total Kinetic Energy of the rigid body is:

$$\begin{split} \mathcal{K} &= \sum_{i} \frac{1}{2} m_{i} \vec{v}_{i}^{2} = \sum_{i} \frac{1}{2} m_{i} (\vec{v}_{CM}^{2} + 2 \vec{v}_{CM} \cdot \vec{V}_{i} + \vec{V}_{i}^{2}) \\ &= \frac{1}{2} (\sum_{i} m_{i}) V_{CM}^{2} + \frac{1}{2} \sum_{i} m_{i} \vec{V}_{i}^{2} + \vec{v}_{CM} \cdot \sum_{i} m_{i} \vec{V}_{i} \end{split}$$

The first terms is the translational kinetic energy
The second term is the rotational kinetic energy around the contractional kinetic energy

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PHYS109 165 / 175

# Kinetic Energy of A Rotating Object That also Has Translational Motion

• Total Kinetic Energy of the rigid body is:

$$\begin{split} \mathcal{K} &= \sum_{i} \frac{1}{2} m_{i} \vec{v}_{i}^{2} = \sum_{i} \frac{1}{2} m_{i} (\vec{v}_{CM}^{2} + 2 \vec{v}_{CM} \cdot \vec{V}_{i} + \vec{V}_{i}^{2}) \\ &= \frac{1}{2} (\sum_{i} m_{i}) V_{CM}^{2} + \frac{1}{2} \sum_{i} m_{i} \vec{V}_{i}^{2} + \vec{v}_{CM} \cdot \sum_{i} m_{i} \vec{V}_{i} \end{split}$$

- The first terms is the translational kinetic energy
- The second term is the rotational kinetic energy around the CM.
- The third term is zero since  $\sum_i m_i \vec{V}_i$  is the total momentum relative the the *CM* which is zero.
- $K = \frac{1}{2}Mv_{CM}^2 + \frac{1}{2}I\omega^2$
- Note that this simple form is valid only if one considers are to the physics of the

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PHYS109 165 / 175

### Work Done On a Rotating Object

- $W = \int_{P_i}^{P_f} \vec{F} \cdot d\vec{\ell}$
- $d\ell = Rd\theta$
- $\vec{F} \cdot d\vec{\ell} = FRd\theta \cos \gamma$ , where  $\gamma$  is the angle between  $\vec{F}$  and  $d\vec{\ell}$
- $F \cos \gamma$  is the component of  $\vec{F}$  along  $d\vec{\ell}$
- $d\ell$  is perpendicular to  $\vec{R}$ .
- Hence  $F \cos \gamma = F_{\perp}$

$$m{W}=\int_{ heta_i}^{ heta_f}m{F}_otam{R}m{d} heta=\int_{ heta_i}^{ heta_f} aum{d} heta$$

• The power is:

$$\boldsymbol{P} = \frac{dW}{dt} = \tau \frac{d\theta}{dt} = \tau \omega$$



Torque

#### Work Energy Principle For Rotations

$$W = \int_{\theta_i}^{\theta_f} \tau d\theta = \int_{t_i}^{t_f} I \frac{d\omega}{dt} \frac{d\theta}{dt} dt$$
$$= \int_{t_i}^{t_f} \frac{d\omega}{dt} I \omega dt = \int_{t_i}^{t_f} \frac{d}{dt} \left(\frac{1}{2} I \omega^2\right) dt$$
$$= \frac{1}{2} I \omega_f^2 - \frac{1}{2} I \omega_i^2$$



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#### **Concept Questions**

Object A sits at the outer edge (rim) of a merry-go-round, and object B sits halfway between the rim and the axis of rotation. The merry-go-round makes a complete revolution once every thirty seconds. The magnitude of the angular velocity of Object B is

- A half the angular speed of Object A.
- B the same as the angular speed of Object A.
- C twice the angular speed of Object A.
- D impossible to determine

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Physics

#### **Concept Questions**

Which has the smallest I about its center?

- A Ring (mass m , radius R )
- B Disc (mass m , radius R )
- C Sphere (mass m, radius R)
- D All have the same I.



#### **Concept Questions**

In this problem ignore any friction/drag. Suppose that you release (from rest) an object from a very high building. Where does it fall?

- A straight down
- B a bit to the north
- C a bit to the south
- D a bit to the east
- E a bit to the west



#### QUIZ 6

A mass  $m_1 = 2 kg$  that has a velocity  $\vec{v}_1 = (3 m/s)\hat{x} + (4 m/s)\hat{y}$  collides with a mass  $m_2 = 3 kg$  that moves with a velocity  $\vec{v}_2 = (2 m/s)\hat{y}$ . The two masses stick together.

- What is their common velocity after the collision?
- Output the second se