Quite often the measurements of pressures has to be conducted in unsteady conditions.

Typical cases are those of

-the measurement of time-varying pressure (with periodic oscillations or step changes)

-the pneumatic scanning of several different steady state pressures (using a single pressure transducer)

In these cases, phenomena like the time or frequency response of the pressure measuring system (consisting of pressure tap or probe, pressure line, valves, transducer) and the effect of various parameters of the measuring system have to be considered.

This is necessary in order to avoid measuring errors.

An enclosure where pressure is varying, as a result of any process (moving boundaries, mass-flow input, chemical reaction, heat transfer, phase change, etc...)



Different cases of occurrence of unsteady pressures

An airfoil (or any other body) immersed in an unsteady mainstream, or a steady mainstream but subjected t of change of incidence, periodic or not (oscillating airfoil, or subjected to a pitch-up maneuver)



Different cases of occurrence of unsteady pressures

The case of a test model (aircraft, ground vehicle, airfoil or turbomachinery blade, internal flow system) with a large number of pressure tabs, each one subjected to a steady pressure, and using a pneumatic switching device (scanning valve) to connect in sequence every tap to the same pressure transducer, which is therefore subjected to a succession of pressure steps.



Different cases of occurrence of unsteady pressures

In all the previous cases represented, the measured time-dependent pressure signal P will in general be different from the real time-dependent pressure P_{true} .

For example, in the case of a set of pressures measured using a scanning valve, different possible results of measurements could be obtained, characterized by an oscillating or a non-oscillating response, with a small or a large damping.



Possible results of scanning valve pressure measurements

In general, the response of a pressure measuring system can be examined:

-in the time domain

or

-in the frequency domain, following a usual practice, adopted in the study of the transfer function of any mechanical or electrical system.

When working in time domain, a pressure step is applied to the system and the output is recorded. Several possible output shapes are shown in Figure characterized by an oscillatory or non-oscillatory behavior.

It is important in all these cases to define the "*response time*', i.e. that time interval after application of the pressure step after which the pressure transducer output has reasonably reached the true final steady-state value.



When working in frequency domain, a sinusoidal pressure variation of a given frequency is applied to the measuring system.

The system output will in general also be periodic (or sinusoidal in the particular case of a linear system).

One can then use the ratio of the output to input oscillation amplitudes and an output to input phase lag, plotted versus frequency to characterize the frequency response of the system.



Practical configurations of unsteady pressure measurements systems:

Flush-mounted pressure transducers:

The ideal configuration of a pressure transducer for measuring rapidly varying pressures is that of the flush-mounted transducer.

In this arrangement the sensing membrane of the transducer is located directly on the surface where the pressure has to be **MEMBRANE** measured, thus eliminating the need for a pressure tap, and for a plastic or metal tube connecting the tap to the inner cavity of the transducer.



Practical configurations of unsteady pressure measurements systems:

Flush-mounted pressure transducers:

The tap, the tubing and the internal volume of the transducer, which are present in any other arrangement, generally cause a substantial increase of the response time of the pressure measuring system.

Therefore, the flush-mounted transducers generally yield the minimal response time, limited only by the mechanical response of the membrane for piezo-resistive transducers or of the sensing crystal for piezo-electric transducers.

Examples of pressure transducers that can be flush-mounted:

-"Kistler" and "PCB" piezoelectric transducers (tip diameter of about 5mm) -"Kulite" and "Endevco" piezosensitive transducers, with semiconductor strain gages directly bounded on the sensing membrane (total tip diameter of about 2mm)

Practical configurations of unsteady pressure measurements systems:

Pressure transducer connected to a pressure tap:

The usual type of pressure transducers is characterized by the existence of two internal volumes, separated by the sensing membrane, and connected to the outside by two ports.

In some cases the transducer is symmetrical (e.g. "Validyne") in other cases it is not (e.g. "Statham', with two different internal cavity volumes)



Validyne DP45 pressure transducer

Practical configurations of unsteady pressure measurements systems:

Pressure transducer connected to a pressure tap:

One of the two ports can be the measurement port, the other being a 'reference' port left open

-to ambient pressure(gage pressure measurement)

-to vacuum (absolute pressure measurement)

or both can be used as measurement ports (differential pressure measurements)



Schematic representation of pressure transducer (for gage or absolute pressure measurement)

Practical configurations of unsteady pressure measurements systems:

Pressure transducer connected to a pressure tap:

In the case of the differential pressure measurement, a second connecting line and pressure tap must be added to the right port.



Schematic representation of pressure transducer (for gage or absolute pressure measurement)

Practical configurations of unsteady pressure measurements systems:

Pressure transducer connected to a pressure tap:

When a pressure is applied, the membrane deforms, causing a variation of both internal cavity volumes. This variation is defined as the "displacement volume" of the pressure transducer, and together with the "cavity volume" (in the non-deformed membrane situation) characterizes the unsteady response capability of the specific pressure transducer.

However, these two volume parameters alone DO NOT define the unsteady response of a pressure measuring system.

This response also depends on the <u>connecting line</u> <u>length</u> and <u>diameter</u>, on the <u>pressure tap</u> <u>dimensions</u>, on the <u>absolute pressure level</u> over which a pressure variation is considered.



Pressure transducer connected to a pressure tap:

Physically, time response of the measuring system is limited by the following succession of phenomena:

After a pressure step increase at the pressure tap location <u>a pressure wave will form</u> and will travel along the connecting line towards the pressure wave will be reflected (as a compression or expansion wave, depending on conditions: dead-end line, or transducer with large inner volume) and will travel back and forth a number of times until it quickly damps out.

In the same time, some flow will be initiated in the connecting line, and fluid will flow into the transducer,

-to cause a pressure increase inside the transducer (the required amount of fluid, due to its compressibility, depends on the cavity volume and on the absolute pressure level)
-to compensate for the membrane deformation (the required amount of fluid depends on the displacement volume and on the amplitude of pressure step)

The rate at which this will occur will also depend on the pressure loss characteristics of the connecting line, wall pressure tapping, or type of pressure probe used (static, total, multiple-holes).

This is different from the steady state situation, in which there is no flow in the connecting line, and no need to consider its pressure loss characteristics.

Pressure transducer connected to a pressure tap:

It is absolutely wrong to speak about the time, or frequency of a specific pressure transducer.

Rather one has to speak about the time or frequency response of a measuring system (transducer, plus line, plus possible fittings, plus pressure tap, or internal flow characteristics of a pressure probe)

Practical configurations of unsteady pressure measurements systems:

Multiple pressures measurement using scanning valve:

When a large number of pressures has to be measured, the use of a scanning valve is a must, as it greatly reduces the required number of transducers, and therefore the total cost of instrumentation, and also simplifies the transducer calibration procedure.





48 position scanning valve

Practical configurations of unsteady pressure measurements systems:

Multiple pressures measurement using scanning valve:

At the moment of the switching from one position to the next, the portion of the line connected to the next pressure tap is at the correct pressure, different from the pressure existing in the line connected to the pressure transducer.

To minimize the response time of this kind of system, the length and volume of the line connecting the scanning valve to the pressure transducer have to be reduced as much as possible, and that the length and diameter of the lines to the pressure taps have a much smaller effect.



Schematic representation of scanning valve/ pressure transducer

Practical configurations of unsteady pressure measurements systems:

Multiple pressures measurement using electronic pressure scanner:

An alternative to the use of scanning valves for the measurement of a large number of pressures is the use of an electronic pressure scanner.

This consists in a number of individual pressure transducers, assembled together in a module (with 16, 32 or 64 transducers each), each transducer individual port being permanently connected to the tap where pressure has to be measured.

The switching from one measurement to another is done electronically, by sampling in sequence the output of each pressure transducer.



Electronic pressure scanner (32 transducer modules)

Multiple pressures measurement using electronic pressure scanner:

Another alternative is the use of a large number of individual low cost pressure transducers, connected to a data acquisition system with a sufficiently large number or channels.



Large number of individual transducers



Supplying a digital I2C output, the differential pressure sensor measures with highest sensitivity and accuracy even at low differential pressures (< 10 Pa).

Version:	Connection:	Calibrated range:	Accuracy:
SDP600	Manifold connection	-500 to 500 Pa	0.5 Pa + 3% of reading
SDP610	Tube connection	-500 to 500 Pa	0.5 Pa + 3% of reading
SDP500	Manifold connection	0 to 500 Pa	0.5 Pa + 4.5% of reading
SDP510	Tube connection	0 to 500 Pa	0.5 Pa + 4.5% of reading

http://www.sensirion.com/en/04_differential_pressure_sensors/01_sdp600-differential-pressure-sensors/00_sdp600-differential-pressure-sensors.htm

Practical configurations of unsteady pressure measurements systems:

Practical tips for pressure transducer connecting:

In practice, the pressure tap, or the holes in a pressure probe do not have the same diameter as the pressure line. The line could be made of a number of tubes with different diameter, connected together by adaptor fittings.





Schematic representation of various practical pressure transducer systems

Practical configurations of unsteady pressure measurements systems:

Practical tips for pressure transducer connecting:

•Using large line and a very small internal volume transducer lead to a pneumatic scheme resembling that of a dead-end tube.



Schematic representation of various practical pressure transducer systems

Practical configurations of unsteady pressure measurements systems:

Practical tips for pressure transducer connecting:

An incorrect fitting between the line and the transducer severely compromising the system response time.



Schematic representation of various practical pressure transducer systems

Practical configurations of unsteady pressure measurements systems:

Most pressure transducers have input ports with diameters around 4 to 6 mm, and most pressure tappings in models are done using 1 mm or 1.5 mm tubing.

For instance, below Figure depicts a common but completely wrong practice, if response time has to be minimized.



Practical configurations of unsteady pressure measurements systems:

It is better to custom build a special adapter, with same diameter as the line, directly fitted to the pressure transducer.



Correct adaptor fitting to pressure transducer

Analysis of the pressure response of a line-cavity system

The step response of the simplest line-cavity system:

Figure shows schematically a pressure transducer connected to a pressure tap of same diameter as the connecting line. At time t=0, a pressure step of amplitude P_0 , over an initial absolute pressure P_a , is applied at tap location.

At t=0, the pressure in the line (from locations 1 to 2) and in the cavity 3 of the transducer is at the initial value P_a .

The fluid in the line starts moving, and the pressure in cavity 3 will rise.



Analysis of the pressure response of a line-cavity system



Analysis of the pressure response of a line-cavity system

Fluid behaviour in line:

The whole amount of fluid contained in the line, of cross sectional area S, will be subjected to a force $S(P_1-P_2)$ causing it to accelerate. A dynamic balance, equating this force to the sum of fluid inertia and wall friction forces will yield:

$$S(P_1 - P_2) = \rho \ell \frac{dU}{dt} S + \pi \, d\,\ell\,\tau_w$$



Analysis of the pressure response of a line-cavity system

Fluid behaviour in line:

Assuming that the wall friction coefficient in unsteady conditions is the same as that in steady flow conditions (this is the weak point of this method), we can use the relations for steady pipe flow:

$$\pi d\ell \tau_w = S \ \Delta P$$

where ΔP , steady state pipe pressure loss is given by the sum of a distributed pressure loss

$$\Delta P = 4C_f \frac{\ell}{d} \rho \frac{U^2}{2} \qquad \begin{array}{c} C_f = 16/Re \\ C_f = 0.08Re^{-1/4} \end{array} \quad \text{in the laminar flow case, or} \\ \text{in the turbulent smooth wall case} \end{array}$$

and of localized pressure losses (e.g. at pipe inlet, outlet, bends, branchings...)

$\Delta P = \xi \ \rho \ \frac{U^2}{2}$	$\begin{aligned} \xi &= 0.5\\ \xi &= 0\\ \xi &= 1\\ \xi &= 4/2 \end{aligned}$	pipe entrance, wall tap with sharp edges pipe entrance, wall tap with rounded edges, or total head probe pipe exit, turbulent flow
	$\xi = 4/3$	pipe exit, laminar flow

Analysis of the pressure response of a line-cavity system

Fluid behaviour in line:

So the dynamic balance equation becomes:

$$\frac{P_1 - P_2}{\rho} = \ell \frac{dU}{dt} + \left(4C_f \frac{\ell}{d} + \xi_1 + \xi_2 + \dots\right) \frac{U^2}{2}$$

In the case of <u>turbulent flow</u>, and explicitly making the exit pressure loss term $\xi=1$:

$$\frac{P_1 - P_2}{\rho} = \ell \frac{dU}{dt} + (1+k)\frac{U^2}{2} \qquad k = 4C_f \,\frac{\ell}{d} + \xi_{in} + \xi_{bends}$$

In the case of laminar flow:

$$\frac{P_1 - P_2}{\rho} = \ell \frac{dU}{dt} + 32\nu \frac{\ell}{d^2}U + \left(\frac{4}{3} + \Sigma\xi\right)\frac{U^2}{2}$$
$$= \ell \frac{dU}{dt} + k_1U + k_2\frac{U^2}{2}$$

Analysis of the pressure response of a line-cavity system

Fluid behaviour in line:

•These first order, non-linear equations describe the unsteady flow in the line connecting pressure transducer to tap or probe.

•The choice between laminar and turbulent flow case is given by the value of the pipe Reynolds number Re=U d/ ν (smaller or larger than about 2000)

Analysis of the pressure response of a line-cavity system

Fluid behaviour in cavity:

To describe the increase of pressure (P_3 - relative pressure with respect to absolute pressure P_a) in the transducer cavity, mass conservation equation is used equating the mass flow entering the cavity to the time variation of mass contained in the cavity:

$$\rho US = \frac{a}{dt}(V_{ol}.\rho)$$

$$US = \frac{dV_{ol}}{dt} + \frac{V_{ol}}{\rho}\frac{d\rho}{dt}$$

where volume of the cavity V_{ol} must be considered as a variable since the pressure transducer membrane deforms in time.

 V_{ol} is not directly a function of time but rather of pressure P_3 , and this latter is a function of time.

$$\frac{dV_{ol}}{dt} = \frac{dV_{ol}}{dP_3} \cdot \frac{dP_3}{dt}$$

Analysis of the pressure response of a line-cavity system

Fluid behaviour in cavity:

A polytropic compression takes place inside the cavity:

 $\frac{dP}{P} = n \frac{d\rho}{\rho} \qquad \qquad n = 1 \text{ for a very slow, almost isothermal compression} \\ n = 1.4 \text{ for a fast adiabatic compression (diatomic gas)}$

The mass conservation equation then becomes:

$$US = \left(\frac{dV_{ol}}{dP_3} + \frac{V_{ol}}{nP}\right)\frac{dP_3}{dt}$$

where $P = P_a + P_3$, as P_3 is a relative pressure.

Assuming that the pressure step P_3 is small compared to initial pressure P_a , as in most cases in practice

$$US = \left(\frac{dV_{ol}}{dP_3} + \frac{V_{ol}}{nP_a}\right)\frac{dP_3}{dt}$$

Analysis of the pressure response of a line-cavity system

Fluid behaviour in cavity:

As pressure transducers are designed to be linear instruments, the quantity dV_{ol}/dP_3 is a constant given by

 dV_{ol}/dP_3 = displacement volume / transducer pressure range

and therefore integration of the expression, with initial condition $P_3=0$ yields:

$$P_{2}(t) = P_{3}(t) = \frac{1}{\frac{dV_{ol}}{dP_{3}} + \frac{V_{ol}}{nP_{a}}} \int \underbrace{USdt}_{VOlume flow rate}$$

Analysis of the pressure response of a line-cavity system

Fluid behaviour in cavity:

Analogy between fluid flow and electricity:

Fluid



P, Pressure Volume flow rate



V, Voltage I, Current

Electricity

 $V = \frac{1}{C} \int I dt$

$$C = \frac{dV_{ol}}{dP_3} + \frac{V_{ol}}{nP_a}$$

Fluidic capacitance due to transducer inner volume and is the parameter fully charecterizing the behaviour of the transducer volume alone.

Analysis of the pressure response of a line-cavity system

Fluid behaviour in cavity:

C is not only dependent on the internal volume and on the displacement volume, but also in on the transducer pressure range (pressure variation over which the total displacement volume occurs) and on the absolute level of pressure at which the transducer is used.

Thus physically the same transducer, with a given internal volume, displacement volume and differential pressure range, will exhibit a larger capacity (therefore increasing response time of the system) at low absolute pressures P_a .

$$C = \frac{dV_{ol}}{dP_3} + \frac{V_{ol}}{nP_a}$$

Analysis of the pressure response of a line-cavity system

<u>Combined line-cavity system:</u>

Eliminating the variable $P_2=P_3$ in the line and cavity equations, we obtain:

$$\frac{P_1}{\rho} - \frac{S}{\rho C} \int U dt = \ell \frac{dU}{dt} + k_1 U + k_2 \frac{U^2}{2}$$

valid in the laminar flow case, but also representing the turbulent case (with $k_1=0$ and $k_2=1+k$)

This is a first order integro-differential equation, with initial condition

U=0 at t=0

The integral can be eliminated by differentiation, obtaining the non-linear, second order differential equation

$$\ell \frac{d^2 U}{dt^2} + (k_1 + k_2 U) \frac{dU}{dt} + \frac{S}{\rho C} U \approx 0$$

with two initial conditions

U=0 and $dU/dt=P_1/\rho I$ at t=0

Analysis of the pressure response of a line-cavity system

<u>Combined line-cavity system:</u>

$$\ell \frac{d^2 U}{dt^2} + (k_1 + k_2 U) \frac{dU}{dt} + \frac{S}{\rho C} U = 0$$

This equation can be solved numerically by a classical single-step time-marching technique (e.g. 4th order Runge-Kutta scheme)

Once **U(t)**, i.e. the variation in time of the average velocity in the line is known, the pressure P_3 in the transducer cavity can be obtained from the equation derived previously:

$$P_{3} = \frac{1}{C} \int_{0}^{t} USdt$$

$$\begin{cases} k_{A} = k_{2}/\ell = (4/3 + \Sigma\xi)/\ell \\ k_{B} = S/\rho C\ell \\ k_{C} = k_{1}/\ell = 32\nu/d^{2} \\ k_{D} = S/C \end{cases}$$



constant its length)



Analysis of the pressure response of a line-cavity system

Combined line-cavity system:



 $k_A = k_2/\ell = (4/3 + \Sigma\xi)/\ell$ $k_B = S/\rho C\ell$ $k_C = k_1/\ell = 32\nu/d^2$ $k_D = S/C$

The behavior of the system changes from that of an oscillating second order system to that of a damped second order system, then to that of a first order system.

Analysis of the pressure response of a line-cavity system

<u>Combined line-cavity system:</u>

Figure below shows results of calculations for a system that can be considered of first order, as a result of the use of a transducer with a relatively large inner volume and of a line with a relatively small diameter.



Calculated and measured time response of non-oscillating line-cavity system ΔP = 200 mm Hg =6V, d=1 mm)

Analysis of the pressure response of a line-cavity system

<u>Combined line-cavity system:</u>

The figure shows the effects of varying line diameter and length, and also clearly shows the difference between the system time constant τ_1 (based on extrapolation of the curve slope at origin) and the system response time τ (when the transducer output reaches the true value).



Calculated and measured time response of non-oscillating line-cavity system ΔP = 200 mm Hg =6V, d=1 mm)

Analysis of the pressure response of a line-cavity system

Combined line-cavity system:



Calculated and measured time response of non-oscillating line-cavity system ΔP = 200 mm Hg =6V, d=1 mm)

Analysis of the pressure response of a line-cavity system

Simplified Linear Analysis of unsteady pressure measuring systems:

In some cases non-linear terms of previous second order differential equation can be neglected. This happens when two conditions are both verified:

Flow inside the line must be laminar and the velocity in the line must be sufficiently low or the line is very long, or the diameter is sufficiently small so that the laminar pressure drop (proportional to the velocity U) results to be much larger than the pressure drop associated with dynamic pressure losses (occurring at line exit, bends or section changes), which are proportional to U^2 , also in the case of laminar flow.

In such case, the term ${\bf k}_2$ is small compared to ${\bf k},$ and the equation can be linearized as:

$$\ell \frac{d^2 U}{dt^2} + k_1 \frac{dU}{dt} + \frac{S}{\rho C} U = 0$$

Analysis of the pressure response of a line-cavity system

Simplified Linear Analysis of unsteady pressure measuring systems:



According to this analogy, the resistive behaviour of a line is due to viscous pressure losses.

L: Inductance

Analysis of the pressure response of a line-cavity system

Simplified Linear Analysis of unsteady pressure measuring systems:



According to this analogy, the inductive behaviour of a line is due to inertia of the fluid contained in it.

Analysis of the pressure response of a line-cavity system

Simplified Linear Analysis of unsteady pressure measuring systems:

Electricity L: Inductance R: resistance C: Capacitance I: Current V: Voltage



P, Pressure Q=US, Volume flow rate $C = \frac{dV_{ol}}{dP_3} + \frac{V_{ol}}{nP_a}$ V, Voltage I, Current

Analysis of the pressure response of a line-cavity system

Simplified Linear Analysis of unsteady pressure measuring systems:

To assess the behaviour of a linearizable pressure measuring system, the quantities R, L and C can be evaluated using the formulas and used to solve the second order linear equation.

Depending on the natural frequency

$$\omega_n = \sqrt{1/LC}$$

and on the damping coefficient of the system $\mathcal{P} = \mathcal{P} / \mathcal{P} \mathcal{I}$

 $\zeta = R / 2L\omega_n$

The solution of second order equation is given in Figure, showing oscillating and non oscillating behaviour.



Analysis of the pressure response of a line-cavity system

Simplified Linear Analysis of unsteady pressure measuring systems:

The behaviour of a line may be predominantly resistive (due to viscous losses), or predominantly inductive (due to fluid inertia), depending on the relative importance of the effects of R and L.

$$\frac{L}{R} = \left(\rho \frac{l}{S}\right) / \left(\frac{128}{\pi} \mu \frac{l}{d^4}\right) = \frac{d^2}{32\nu}$$

Therefore, the type of behaviour of a line will not depend on its length, but only on its diameter, and on the kinematic viscosity of the fluid contained in it. Dimensionally L/R is a time, and thus we can define the line time constant:

$$\frac{L}{R} = \tau_l$$

Analysis of the pressure response of a line-cavity system

Simplified Linear Analysis of unsteady pressure measuring systems:

Analogy with electric circuit with a resistance and an inductance in series:

$$V = RI + L \frac{dI}{dt}$$
 with I=0 at t=0

The solution is asymptotically approaching the final steady state value V/R:

$$I = \frac{V}{R} \left(1 - \exp(-t / \tau_l) \right)$$

where $\tau_l = \frac{L}{R}$ is the circuit time constant, characterizing the initial speed of

variation of current.

Therefore, to determine whether a given line has an inductive or a resistive behaviour, one has to compare the line time constant τ_{I} with typical observation time.

Analysis of the pressure response of a line-cavity system

Simplified Linear Analysis of unsteady pressure measuring systems:

Thus if

Observation time $<< \tau_1$ inductive effects predominate

Observation time >> τ_1 resistive effects predominate

and observation time is the response time to reach steady state value.

In addition, when line resistive effects predominate, the inductive second order term can be neglected in the second order system equation, which is then reduced to a first order equation:

$$R\frac{dI}{dt} + \frac{I}{C} = 0$$

Characterized by a time constant τ_1 =RC and a response time (time to approach final state within 1%) τ_r =4.6 RC

Analysis of the pressure response of a line-cavity system

Simplified Linear Analysis of unsteady pressure measuring systems:

A quick estimation of the behaviour of a line and pressure transducer system, approximated by a linear equation, can be conducted as follows:

First calculate the response time for a first order system τ_1 And the time line constant τ_l

Then if $\tau_1 << \tau_1$ inductive effects occur only at the very beginning of the phenomenon and can be neglected so that the response time τ_r =4.6RC

Otherwise, if $\tau_1 >> \tau_{1,}$ inductive effects are present during all the time and the full second order equation must be used:

$$L\frac{d^2Q}{dt^2} + R\frac{dQ}{dt} + \frac{Q}{C} = 0 \quad \square \longrightarrow \quad \frac{d^2Q}{dt^2} + \frac{1}{\tau_l}\frac{dQ}{dt} + \frac{Q}{\tau_l\tau_1} = 0$$

Analysis of the pressure response of a line-cavity system

Simplified Linear Analysis of unsteady pressure measuring systems:

$$\frac{d^2Q}{dt^2} + \frac{1}{\tau_l}\frac{dQ}{dt} + \frac{Q}{\tau_l\tau_1} = 0$$

Type of solution (oscillating or not) of this equation will be determined by the sign of discrement: $\boldsymbol{\tau}$

$$\Delta = b^2 - 4ac = 1 - 4\frac{\tau_1}{\tau_1}$$

$$\begin{split} &\Delta = 0 \Longrightarrow 1 = 4 \frac{\tau_l}{\tau_1} \Longrightarrow \tau_1 = 4 \tau_l & \text{The system is critically damped} \\ &\Delta > 0 \Longrightarrow 1 - 4 \frac{\tau_l}{\tau_1} > 0 \Longrightarrow \tau_1 > 4 \tau_l & \text{The system is over-damped (no oscillation} \\ &\Delta < 0 \Longrightarrow 1 - 4 \frac{\tau_l}{\tau_1} < 0 \Longrightarrow \tau_1 < 4 \tau_l & \text{The system is under damped (oscillation)} \end{split}$$

The system is over-damped (no oscillation)